
Random beam test analysis issues

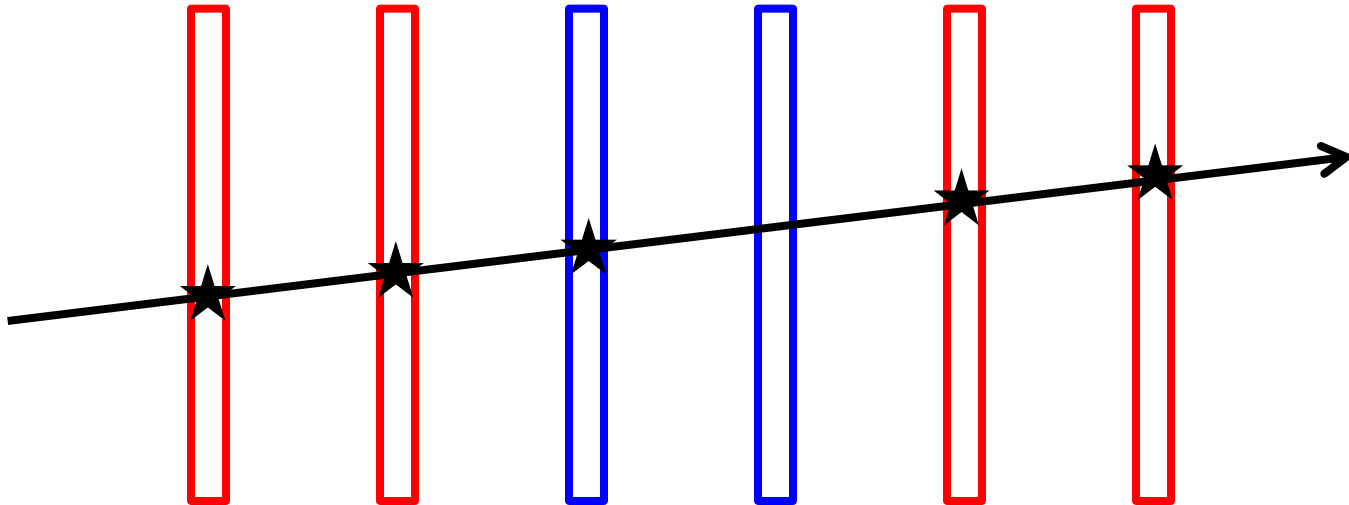
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Basic aims of beam test(s)

- Verify **performance** of TPAC
 - Efficiency for MIPs, noise, number of hits...
- Match TPAC performance to **simulation** using tracks
 - Sensor simulation: compare different sensors (hi-res, deep p-well)
 - GEANT4 simulation: rates of hits, MIP efficiencies vs threshold
 - Can be done with pion or electron beams, without tungsten converter
- Measure number of hits (and other properties) of **EM showers**
 - Number of hits vs energy, shower width at various depths in X_0
 - Verify (or not) GEANT4 simulation of EM showers at very high granularity
 - Must have electron beams for this with tungsten converter to generate EM showers
- Must know **efficiency** from first part to do second part
 - This is the main point of the CERN beam test

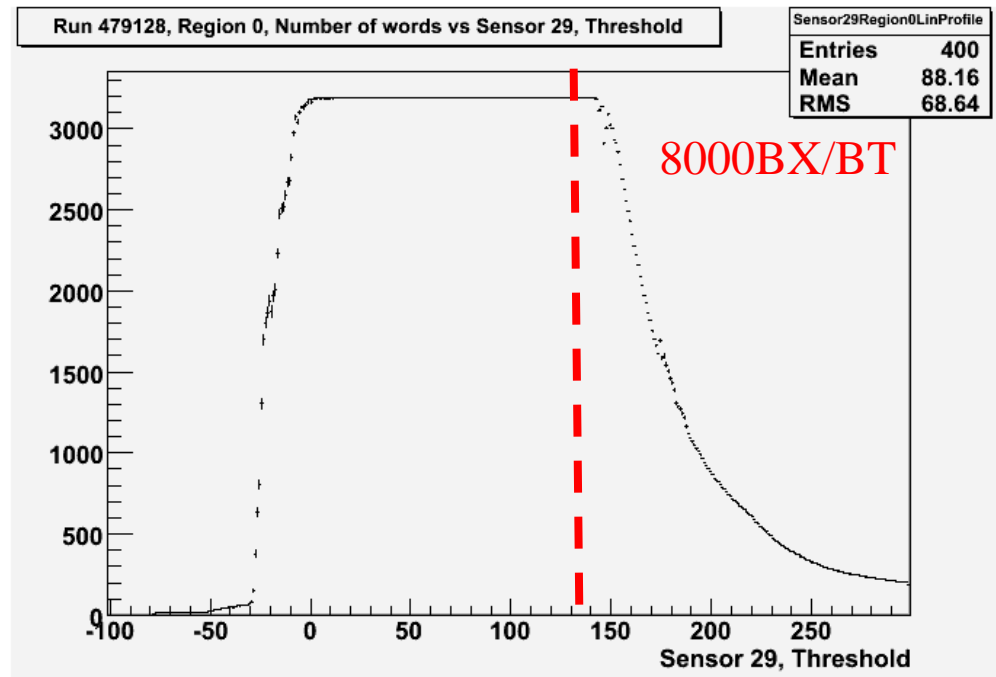
How do we measure efficiency?

- **Five or six** layers of sensors
 - Treat central one or two as “sensors-under-test”
 - Vary their parameters (threshold, masking, etc)
 - Keep outer two upstream and downstream sensors fixed
- Form tracks from **outer** sensors and project into **inner** sensors
 - Measure fraction of times a hit is found near projection to give efficiency
 - Easy, right?



Noise rate

- Average noise is $\sim 7\text{TU}$, so $5\sigma \sim 35\text{TU}$
- Pedestal is fixed to 100TU by trimming
- Ideal threshold $\sim 135\text{TU}$ but memory saturates at this threshold
- Due to few pixels with high noise
- Need to mask these, probably $\sim \text{few } \%$ but direct impact on **efficiency**
- Assume hit rate $\sim 5\text{k}$ per sensor per BT



Other efficiency effects

- Sensor has **dead** areas
 - Four 250 μ m-wide strips vertically
 - One 50 μ m-wide strip horizontally
 - Total active area 88.8% within nominal sensitive area
 - May also have tracks hitting outside sensitive area if sensors misaligned
 - Want to correct for this in efficiency, i.e. we want the efficiency for an active pixel, not of whole sensor
- Memory will **saturate** at 19 hits per row
 - Tracks at end of bunch train may have lower efficiency than at beginning
 - Can identify exactly when each row filled
 - Again, want to correct efficiency for this effect
- In all three cases (masking, dead areas, memory saturation)
 - Would need to know **where** hit was “supposed” to be if correcting at a track-by-track level
 - Masking needs us to know within a single pixel, memory a single row

Accuracy of track projection

- Resolution of projection $\sim \sigma_{\text{outer}}/2$
 - Assuming sensors equally spaced, negligible scattering
- If each hit in outer sensors located to one pixel
 - Implies $\sigma_{\text{outer}} \sim 50\mu\text{m}/\sqrt{12} \sim 14\mu\text{m}$ so projection **resolution $\sim 7\mu\text{m}$**
- But will in general have some **nearest neighbours** fire too
 - Do we set threshold in outer sensors much higher to cut down neighbour hits?
 - Reduces outer sensor efficiency and hence rate of usable four-hit tracks
 - Depends on (currently unknown) beam rate
- Even $7\mu\text{m}$ resolution is **not ideal**
 - If “definitely in a pixel” means 2σ from edge, then only $\sim 20\%$ of pixel surface will be used (and is a biased sample, not over whole pixel surface)
 - Cannot do a “per-track” hit efficiency correction easily
 - How do we correct for the “artificial” inefficiencies? Statistically?

Noise rate implications

- Noise rate likely to be **~5k hits/BT** for each sensor
 - This is ~0.5hit for each BX during an 8000 BX train
- If PMTs work well, coincidences **time-tag** the beam particle
 - Need to look at hit maybe within ± 1 (?) timestamp of PMT hits (plus potentially some fixed time alignment offset)
 - Will have ~1-2 noise hits within this time window in each sensor
 - Beam particle will give a similar number if sensor is efficient
- For making tracks in **outer sensors**
 - Need to do correlations also in space to identify real hits
 - Effectively track pattern recognition; need alignment at what level?
 - Do we allow tracks with only three of the four outer sensors included?
- For efficiency from **inner sensors**
 - Cannot just ask for any hit within time window
 - Probably always a hit somewhere so again need hit close to projection

Conclusions

- Main aim of CERN beam test is **MIP efficiency** measurement
 - Assuming no electron beam available
- Efficiency calculation is **not trivial**
 - Need to do full alignment of sensors
 - Need to have track pattern recognition and fit reconstruction code
 - Need to consider masking, dead areas and memory saturation effects
- Ideally would start on this **before** doing to the beam test
 - Can use MC data for this