Answers 6
(1) The figure on the right shows a possible circuit. The comparator thresfold is set to half the maximum amplitude of the input signal. The signals at different points in the circuit should look as shown in the figure below.


If the clock and the delayed clock are applied to an $x O \mathcal{R}$ input the output is as shown. If the delay is $\mathcal{T}$ and the original clock has period $4 \mathcal{T}$, the resulting waveform is a clock with period $2 \mathcal{T}$.

(2) You can make truth tables or rely on algebraic logic, once you fave a few results.
$\mathcal{A}(\mathcal{B}+\mathcal{C})=\mathcal{A B}+\mathcal{A C}$

$$
\begin{array}{ll}
\mathcal{A}+\mathcal{A B}=\mathcal{A} & \mathcal{A B}=\mathcal{A} \text { or } 0,6 \text { ut } \mathcal{A}+0=\mathcal{A}=\mathcal{A}+\mathcal{A} \\
\mathcal{A}+\mathcal{B C}=(\mathcal{A}+\mathcal{B})(\mathcal{A}+\mathcal{C}) & \text { use the previous results } \\
\mathcal{A A}^{\prime}=0 & \text { either } \mathcal{A} \text { or } \mathcal{A} \prime^{\prime} \text { must }=0 .
\end{array}
$$

and $\mathcal{D e} \operatorname{Morgan's}$ theorems:

$$
(\mathcal{A}+\mathcal{B})^{\prime}=\mathcal{A} \mathfrak{B}^{\prime} \quad \text { and } \quad(\mathcal{A B})^{\prime}=\mathcal{A}^{\prime}+\mathcal{B}^{\prime}
$$

(3) The truth table can be deduced from the logic identities, or from the diagram.
The intermediate results are $\mathcal{A}+\mathcal{B}$ and $\mathcal{B}+\mathcal{C}$ so $Q=(\mathcal{A}+\mathcal{B})(\mathcal{B}+\mathcal{C})=\mathcal{B}+\mathcal{A} \mathcal{C}$

The table below shows the result from both methods.


| $\mathcal{A}$ | $\mathcal{B}$ | $\mathcal{C}$ | $\mathcal{A}+\mathcal{B}$ | $\mathcal{B}+\mathcal{C}$ | $\mathcal{Q}$ | $\mathcal{A C}$ | $\mathcal{B}+\mathcal{A C}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | $\mathbf{0}$ | 0 | $\mathbf{0}$ |
| 0 | 0 | 1 | 0 | 1 | $\mathbf{0}$ | 0 | $\mathbf{0}$ |
| 0 | 1 | 0 | 1 | 1 | $\mathbf{1}$ | 0 | $\mathbf{1}$ |
| 0 | 1 | 1 | 1 | 1 | $\mathbf{1}$ | 0 | $\mathbf{1}$ |
| 1 | 0 | 0 | 1 | 0 | $\mathbf{0}$ | 0 | $\mathbf{0}$ |
| 1 | 0 | 1 | 1 | 1 | $\mathbf{1}$ | 1 | $\mathbf{1}$ |
| 1 | 1 | 0 | 1 | 1 | $\mathbf{1}$ | 0 | $\mathbf{1}$ |
| 1 | 1 | 1 | 1 | 1 | $\mathbf{1}$ | 1 | $\mathbf{1}$ |

(4) Start with the table of codes. The full 4-6it binary to Gray code table is given below. The 3-6it table is just the first 8 entries. The two upper 6 its can easily be recognised as $b_{3}=g_{3}$ and $b_{2}=$ $X O R\left(g_{3}, \mathscr{g}_{2}\right)$. I got the lower two by inspection - and patience. There's probably a simpler way of finding the lower 6its but I haven't spotted it. The figure shows the 4-6it logic. I ust drop the lowest gate for the 3-6it case.


| decimal | Ginary | Gray |
| :---: | :---: | :---: |
| 0 | 0000 | 0000 |
| 1 | 0001 | 0001 |
| 2 | 0010 | 0011 |
| 3 | 0011 | 0010 |
| 4 | 0100 | 0110 |
| 5 | 0101 | 0111 |
| 6 | 0110 | 0101 |
| 7 | 0111 | 0100 |
| 8 | 1000 | 1100 |
| 9 | 1001 | 1101 |
| 10 | 1010 | 1111 |
| 11 | 1011 | 1110 |
| 12 | 1100 | 1010 |
| 13 | 1101 | 1011 |
| 14 | 1110 | 1001 |
| 15 | 1111 | 1000 |

(5) The equation in the $s$-domain is

$$
s^{2} X(s)-a^{2} X(s)=\mathcal{F}(s)
$$

whicf can be written

$$
X(s)=\frac{\mathcal{F}(s)}{\left(s^{2}-a^{2}\right)}=\frac{\mathcal{F}(s)}{2 a}\left[\frac{1}{(s-a)}-\frac{1}{(s+a)}\right]
$$

so the solution is

$$
x(t)=\frac{f(t)}{2 a} \otimes\left(e^{a t}-e^{-a t}\right)
$$

where the symboldenotes convolution.
(6) The amplifier impulse response is $f(t)=t e^{-t}$
a) The transfer function of a single amplifier is then $\quad \mathcal{F}(s)=\frac{1}{(s+1)^{2}}$
6) The transfer function of two amplifiers is

$$
\mathcal{F}_{\text {total }}(s)=\mathcal{F}_{1}(s) \mathcal{F}_{2}(s)=\mathcal{F}(s)^{2}=\frac{1}{(s+1)^{4}}
$$

c) The transform of a ste $p u(t)=1 / s$, so the transform of the output $g(t)$ is the product of the input function and the overall transfer function, so

$$
\mathcal{G}(s)=\frac{1}{s} \mathcal{F}_{\text {total }}(s)=\frac{1}{s(s+1)^{4}}=\frac{\mathcal{A}}{s}+\frac{\mathcal{B}}{(s+1)}+\frac{\mathcal{C}}{(s+1)^{2}}+\frac{\mathcal{D}}{(s+1)^{3}}+\frac{\mathcal{E}}{(s+1)^{4}}
$$

To derive the constants, proceed as shown in the lecture to find

$$
\mathcal{A}=1, \mathcal{E}=\mathcal{D}=\mathcal{C}=\mathcal{B}=-1
$$

(When differentiating for terms like $\mathcal{B}$ and $\mathcal{C}$ remember to include the factor which comes from multiple differentiations, eg $\left.\mathcal{B}=\frac{1}{3!d s^{3}}\left(\frac{1}{s}\right)^{3}\right)$
then

$$
\mathcal{G}(s)=\frac{1}{s}-\frac{1}{(s+1)}-\frac{1}{(s+1)^{2}}-\frac{1}{(s+1)^{3}}-\frac{1}{(s+1)^{4}}
$$

Ulsing a result from the lectures which you can easily prove

$$
\mathcal{L I}\left[t^{n} e^{-t}\right]=\frac{n!}{(s+1)^{n+1}}
$$

we find the system response to be

$$
g(t)=u(t)-e^{-t}-t e^{-t}-\frac{1}{2} t^{2} e^{-t}-\frac{1}{6} t^{3} e^{-t}
$$

(7) a) For times $t \leq 0$

$$
i(t)=\frac{\mathcal{V}}{\mathcal{R}}
$$

6) Eventually, after the opening of the switch, the same current flows as in (a).
c) $V \mathcal{V}-\left(\mathcal{L}_{1}+\mathcal{L}_{2}\right) \frac{d i}{d t}(t)=i(t) \mathcal{R}$

$$
\mathcal{V}-\left(\mathcal{L}_{1}+\mathcal{L}_{2}\right) s I(s)=I(s) \mathcal{R}
$$

$$
\text { where } \mathcal{L}=\mathcal{L}_{1}+\mathcal{L}_{2}
$$

$$
I(s)=\frac{\mathcal{V}}{\mathcal{R}+s\left(L_{1}+\mathcal{L}_{2}\right)}=\frac{\mathcal{V}}{\mathcal{L}\left(\frac{\mathcal{R}}{\mathcal{L}}+s\right)}
$$

So

$$
i(t)=\frac{\mathcal{V}}{\left(L_{1}+\mathcal{L}_{2}\right)} e^{-\mathcal{R} t / \iota}+i(0)=\frac{\mathcal{V}}{\left(\mathcal{L}_{1}+\mathcal{L}_{2}\right)} e^{-\mathcal{R} t / \iota}+\frac{\mathcal{V}}{\mathcal{R}} \quad \text { for } t>0
$$

(8) Before the switch is opened, as before for $t \leq 0, \quad i(t)=\frac{\mathcal{V}}{\mathcal{R}}$

The equations after the switch is opened are

$$
\begin{aligned}
& \mathcal{V}-\mathcal{L} \frac{d i}{d t}(t)=i(t) \mathcal{R}+\frac{Q(t)}{\mathcal{C}}=i(t) \mathcal{R}+\frac{\int_{0}^{t} i(u) d u}{\mathcal{C}} \\
& \mathcal{V}-\mathcal{L} s I(s)=I(s) \mathcal{R}+\frac{I(s)}{s \mathcal{C}}
\end{aligned}
$$

or

$$
\begin{aligned}
& s^{2} \mathcal{L C I}(s)+s I(s) \mathcal{R C}+I(s)=s \mathcal{C V} \\
& I(s)=\frac{s \mathcal{V} \mathcal{V}}{s^{2} \mathcal{L} C+s \mathcal{R} C+1}=\frac{\mathcal{V}}{\mathcal{L}}\left[\frac{\mathcal{A}}{(s-a)}+\frac{\mathcal{B}}{(s-\sigma)}\right]
\end{aligned}
$$

the values of $a$ and $b$ are

$$
a, b=\frac{-\mathcal{R} C \pm \sqrt{(\mathcal{R C})^{2}-4 \mathcal{L C}}}{2 \mathcal{L C}}=-\frac{\mathcal{R}}{2 \mathcal{L}} \pm \sqrt{\left(\frac{\mathcal{R}}{2 \mathcal{L}}\right)^{2}-\frac{1}{\mathcal{L C}}}
$$

The current in the system can be written as

$$
i(t)=(\mathcal{V} / \mathcal{L})\left[\mathcal{A} e^{a t}+\mathcal{B} e^{6 t}\right]+\mathcal{C}
$$

with $\mathcal{A}=a /(a-b) \quad \mathcal{B}=-6 /(a-b)$ and $\mathcal{C}=i(0)=\mathcal{V} / \mathcal{R}$

The system is stable if both poles are in the left half plane. This requires that the square root term in a or 6 should be smaller in magnitude than the first term. This will always be the case, but complex values of $a$ or 6 mean there is a damped oscillatory solution, as you would expect.
(9) In the s-domain, the system response is

$$
\mathcal{Y}(s)=\mathcal{G}_{0}(s) \mathcal{G}_{1}(s) \mathcal{G}_{2}(s) X(s)
$$

Since $x(t)$ is a $\delta$ impulse, $X(s)=1$. The other transfer functions are

$$
\begin{aligned}
& \mathcal{G}_{0}(s)=\frac{1}{s} \quad \mathcal{G}_{1}(s)=\frac{s \tau_{1}}{\left(1+s \tau_{1}\right)}=\frac{s}{(s+2)} \quad \mathcal{G}_{2}(s)=\frac{1}{\left(1+s \tau_{2}\right)}=\frac{3}{(s+3)} \\
& \mathcal{Y}(s)=\frac{3 s}{s(s+2)(s+3)}=\frac{3}{(s+2)(s+3)}=\frac{\mathcal{A}}{(s+2)}+\frac{\mathcal{B}}{(s+3)} \\
& \mathscr{y}(s)=\frac{3}{(s+2)}-\frac{3}{(s+3)} \\
& \text { so } \quad y(t)=3\left(e^{-2 t}-e^{-3 t}\right)
\end{aligned}
$$

(10) The system response is given $6 y$ the equation

$$
\mathcal{A}[x(t)+\mathcal{B} y(t-\mathcal{T})]=y(t)
$$

Laplace transforming, we find

$$
\mathcal{A}\left[X(s)+\mathcal{B} e^{-s \mathcal{T}} \mathcal{Y}(s)\right]=\mathcal{Y}(s)
$$

so

$$
\mathscr{Y}(s)=\frac{\mathcal{A} X(s)}{\left(1-\mathcal{A} \mathcal{B} e^{-s \mathcal{T}}\right)}
$$

We don't know what value of $\mathcal{T}$ will apply (imagine a large auditorium) and we would like the system to be stable for all $\mathcal{T}$ values. This is somewhat different from the case shown in the lectures, since there is no simple pole. However, clearly $\mathcal{Y}(\mathcal{s})$ should always remain finite for stability. Since $e^{-s \mathcal{T}}<1$, we can see that, provided $\mathcal{A B}<1$, this condition can be achieved. This should be possible provided there are no nasty phase shifts associated with reflections or other such phenomena.

$$
\begin{equation*}
f(t)=\frac{t}{\tau} e^{-t / \tau}=\frac{n \Delta t}{\tau} e^{-n \Delta t / \tau}=n a e^{-n a} \tag{11}
\end{equation*}
$$

with $a=\Delta t / \tau$. Ignoring the factor scaling factor $a$ in front, $f_{n}=n e^{-n a}$ and

$$
\mathcal{F}(z)=e^{-a} z^{-1}+2 e^{-2 a} z^{-2}+3 e^{-3 a} z^{-3}+4 e^{-4 a} z^{-4 \ldots} \ldots+n e^{-n a} z^{-n}+\ldots
$$

define $\chi=e^{-a} z^{-1}$

$$
\mathcal{F}(z)=x+2 x^{2}+3 x^{3}+4 x^{4}+\ldots n x^{n}+\ldots
$$

then, rearranging the sum into separate geometrical series which can be summed inde pendently:

$$
\begin{aligned}
\mathcal{F}(z)=x+x^{2}+x^{3}+x^{4}+\ldots x^{n}+\ldots & =x /(1-x) \\
+x^{2}+x^{3}+x^{4}+\ldots x^{n}+\ldots & =x^{2} /(1-x) \\
+x^{3}+x^{4}+\ldots x^{n}+\ldots & =x^{3} /(1-x) \\
+x^{4}+\ldots x^{n}+\ldots & =x^{4} /(1-x)
\end{aligned}
$$

so
ie

$$
\begin{aligned}
& \mathcal{F}(z)=\left(\chi+\chi^{2}+\chi^{3}+\chi^{4}+\ldots \chi^{n}+\ldots\right) /(1-\chi)=\chi /(1-\chi)^{2} \\
& \mathcal{F}(z)=\frac{e^{-a} z^{-1}}{\left(1-e^{-a} z^{-1}\right)^{2}} \\
& \mathcal{F}^{-1}(z)=\frac{\left(1-e^{-a} z^{-1}\right)^{2}}{e^{-a} z^{-1}}=\frac{\left(1-2 e^{-a} z^{-1}+e^{-2 a} z^{-2}\right)}{e^{-a} z^{-1}}=e^{a} z-2+e^{-a} z^{-1} \\
& \mathcal{g}_{n}=e^{a} f_{n+1}-2 f_{n}+e^{-a} f_{n-1}
\end{aligned}
$$

so
with the three weights being the coefficients of the terms. The constant a ignored is only a scaling factor which is not important, unless we are interested in the amplitude after the deconvolution operation.

