

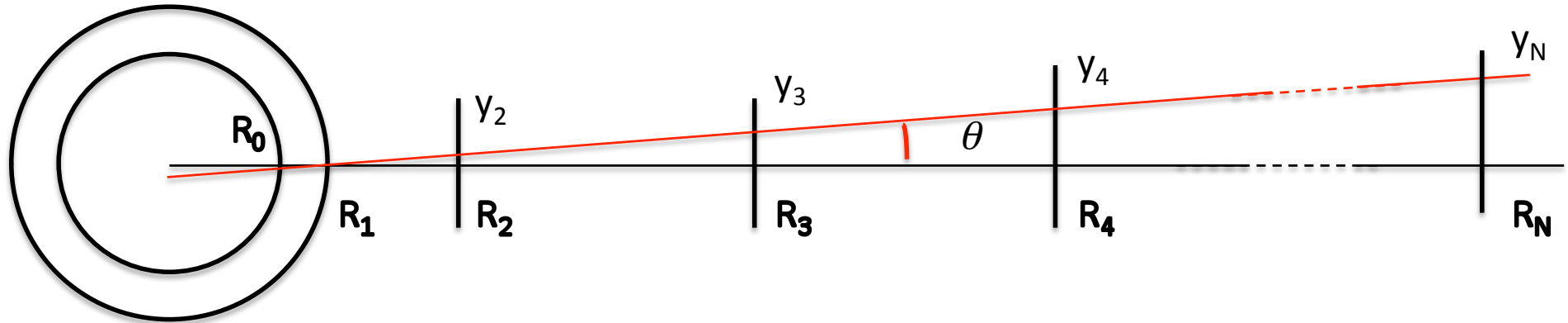
## Calculating Tracker parameters

In view of upgrades to tracker, how much of performance can be estimated without running very lengthy simulations?

Quantities of interest: angular and momentum resolution, impact parameter resolution

Variables: no layers, locations, spatial resolution, material budget

# Impact Parameter estimation



- IP determined by projection to beam from first measurement plane,  $R_1$ 
  - including bending and multiple scattering at beam pipe

$$\sigma_{IP}^2 \approx \sigma_1^2 + R_0^2 \sigma_0^2(\theta_{MS}) + R_1^2 \sigma^2(\theta) + 0.25 R_1^4 \sigma^2(\rho) \quad \rho = 1/R$$

- actually an approximation: should properly include correlations
- Wish to know
  - angular and momentum resolution:  $\sigma(\theta)$ ,  $\sigma(\rho)$  & multiple scattering errors
- Assumes (good approximations)
  - angles are small
  - high enough momentum for curvature  $\rho$  to be small:  $\sim 1 \text{ GeV}/c$

# Impact Parameter calculation

- Linear least squares problem for straight line

$$\chi^2 = \sum_i \frac{(y_i - R_i \theta)^2}{\sigma_i^2} \quad \text{with} \quad \frac{d\chi^2}{d\theta} = 0 \quad \text{has solutions} \quad \theta = \frac{\sum \frac{y_i R_{i1}}{\sigma_i^2}}{\sum \frac{R_{i1}^2}{\sigma_i^2}} \quad \sigma^2(\theta) = \frac{1}{\sum \frac{R_{i1}^2}{\sigma_i^2}}$$

$$R_{i1} = R_i - R_1$$

- More general problem of fitting a circle (helix) to a series of points was solved - in the absence of multiple scattering - by
  - V. Karimäki CMS Note 1997/064 [NIM A410 (1998) 284] & NIM A305 (1991) 187
  - used for track fitting with UA1 wire chambers where MS is minor effect

$$\varepsilon_i \approx \frac{1}{2} \rho r_i^2 - (1 + \rho d) r_i \sin(\phi - \phi_i) + \frac{1}{2} \rho d^2 + d$$

$\rho$  = curvature =  $\pm 1/R$  where R is radius of curvature

$\phi$  = direction of propagation at point of closest approach

d = distance of closest approach to the origin

- general prescription for estimating MS effect is to add spatial errors in quadrature

## Errors from Karimäki calculation

- Covariance matrix:  $W$  and its inverse – **when no correlations present** -

$$W_{kl} = \sum_i w_i \frac{\partial \varepsilon_i}{\partial \alpha_k} \frac{\partial \varepsilon_i}{\partial \alpha_l} \quad w_i = \sigma_i^{-2}$$

$$\rho = \alpha_1 \quad \phi = \alpha_2 \quad d = \alpha_3$$

- Solved explicitly to good approximation

$$\left\{ \begin{array}{l} \sigma_{\rho\rho} = C [4\sigma_{xx} - 4\rho^2(\langle x^2 \rangle^2 - \langle x \rangle \langle xr^2 \rangle + \frac{1}{4}\rho^2 \langle xr^2 \rangle^2)] \\ \sigma_{\rho\phi} = C [2\sigma_{xr^2} - \rho^2(2\langle x^2 \rangle \langle xr^2 \rangle - \langle r^2 \rangle \langle xr^2 \rangle - \langle x \rangle \langle r^4 \rangle + \frac{1}{2}\rho^2 \langle r^4 \rangle \langle xr^2 \rangle)] \\ \sigma_{\phi\phi} = C [\sigma_{r^2r^2} + \rho^2 \langle r^4 \rangle (\langle y^2 \rangle - \frac{1}{4}\rho^2 \langle r^4 \rangle)] \\ \sigma_{\rho d} = C [2\langle x \rangle \langle xr^2 \rangle - 2\langle x^2 \rangle \langle r^2 \rangle - \rho^2(\langle xr^2 \rangle^2 - \langle x^2 \rangle \langle r^4 \rangle)] \\ \sigma_{\phi d} = C [\langle x \rangle \langle r^4 \rangle - \langle r^2 \rangle \langle xr^2 \rangle] \\ \sigma_{dd} = C [\langle x^2 \rangle \langle r^4 \rangle - \langle xr^2 \rangle^2] \end{array} \right.$$

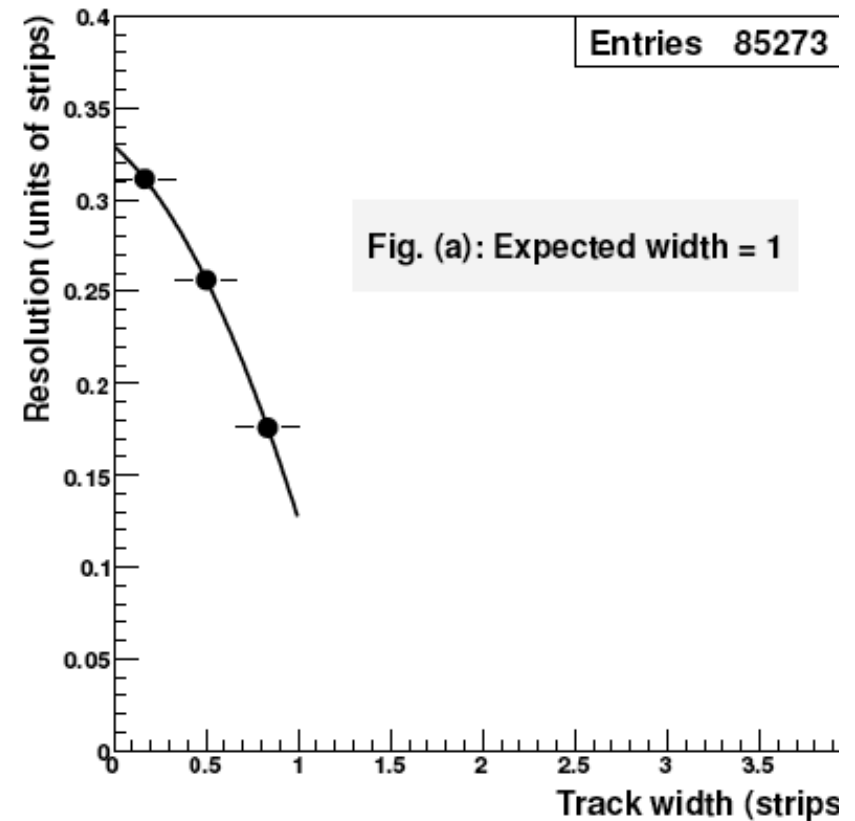
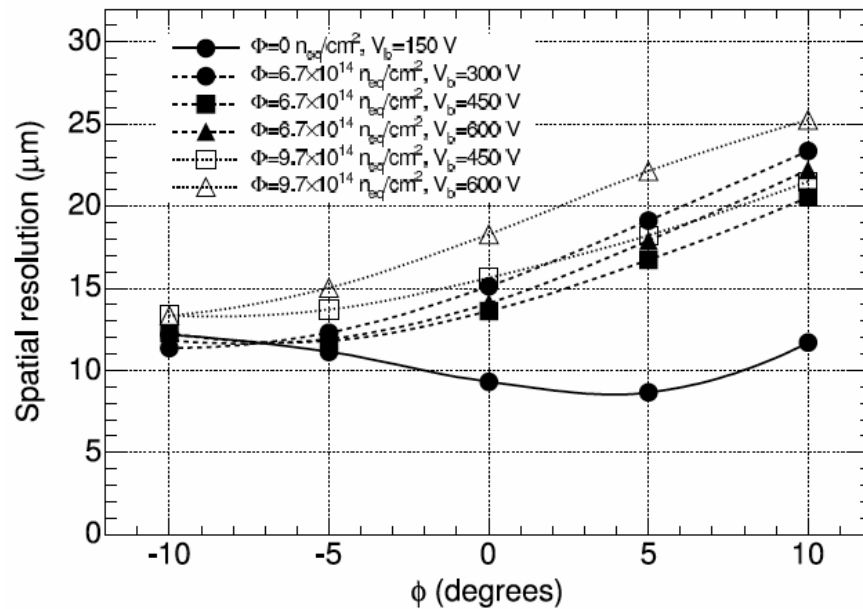
$$\sigma_{ab} = \langle ab \rangle - \langle a \rangle \langle b \rangle \quad \langle u \rangle = \sum w_i u_i / \sum w_i \quad \text{see papers for details}$$

# Measurement error

- $\sigma \approx 10\mu\text{m}$  (pixels)

$\sigma \approx 0.30 \cdot \text{pitch}$  (strips)

better approximation for high p  
at low p MS dominates

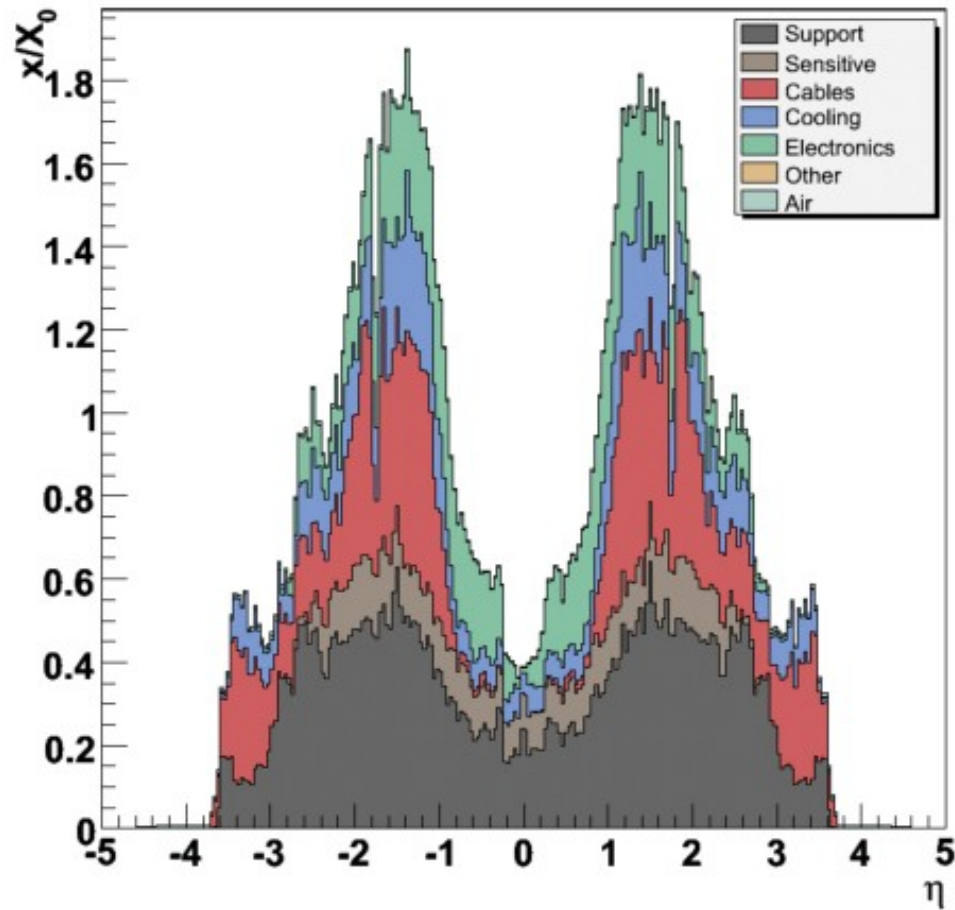


1.2. Expected position resolution of the CMS pixel barrel in the  $r - \phi$  plane as a function of the track angle of incidence.<sup>2</sup> The resolution degrades with increasing fluence and bias voltage because of the reduced charge sharing.

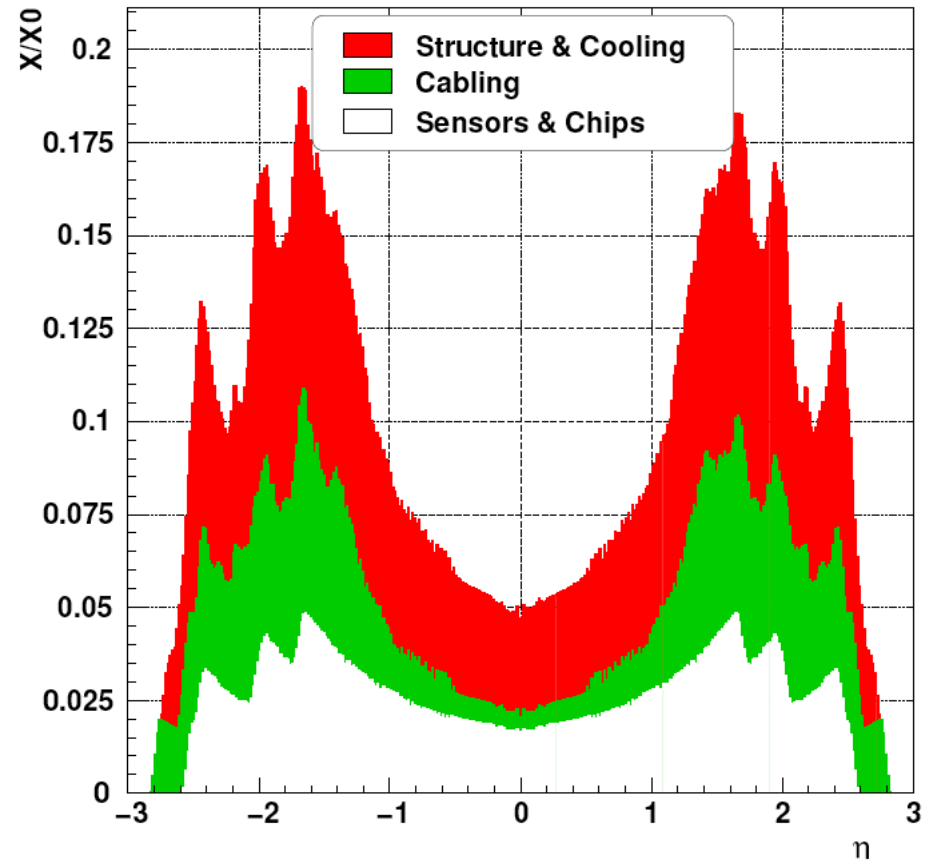
Figure 6.6: Strip tracker cluster position resolution

# Material in present system

Material Budget Tracker



Pixels only



## Simplified model

- Present system: 3 pixel + 10 outer strip
- Each pixel layer assumed identical
  - $t_{\text{eff}} \approx 1.6\text{mm}$  Si equivalent  $\Rightarrow t_{\text{eff}}/X_0 \approx 0.017$  per layer
  - Total  $t_{\text{eff}}/X_0 \approx 0.051$  @  $\eta = 0$
- Outer tracker: two types of layer
  - $t_{\text{eff}} \approx 2.4\text{mm}$  Si equivalent (single)  $\Rightarrow t_{\text{eff}}/X_0 \approx 0.026$  per layer
  - $t_{\text{eff}} \approx 4.84\text{mm}$  Si equivalent (stereo)  $\Rightarrow t_{\text{eff}}/X_0 \approx 0.051$  per layer
  - Total  $t_{\text{eff}}/X_0 \approx 0.359$  @  $\eta = 0$
- Beam pipe
  - $800\mu\text{m}$  Be beam pipe  $\Rightarrow t_{\text{eff}}/X_0 \approx 0.0027$
  - only affects projection back to primary vertex

## Errors assigned for fitting direction

- Combination of measurement + multiple scatter at earlier plane

– multiple scattering dominates  $\theta_0 = \frac{13.6 \text{ MeV}}{\beta c p} z \sqrt{x/X_0} [1 + 0.038 \ln(x/X_0)]$

							<b>p = 1 GeV/c</b>	
i	R		t <sub>eff</sub>	X <sub>0</sub>	t <sub>eff</sub> /X <sub>0</sub>	σ <sub>meas</sub>	σ(θ <sub>MS</sub> )	σ <sub>i</sub>
	[cm]		[cm]	[cm]		[μm]	mrad	[μm]
1	2.9	Be	0.08	35.28	0.0023		0.50	
2	4.4	Si	0.16	9.36	0.017	10	1.53	12
3	7.3	Si	0.16	9.36	0.017	10	1.53	51
4	10.2	Si	0.16	9.36	0.017	10	1.53	102
5	25.5	Si	0.46	9.36	0.051	24	2.72	501
6	34.7	Si	0.46	9.36	0.051	24	2.72	789
7	43.9	Si	0.23	9.36	0.025	36	1.89	1143
..	..		..	..	..	..	..	..
14	108.3	Si	0.23	9.36	0.026	36	2.15	7073

small corrections for incident angle

$$t_{\text{eff}} = t_{\text{layer}} / \cos(\alpha)$$

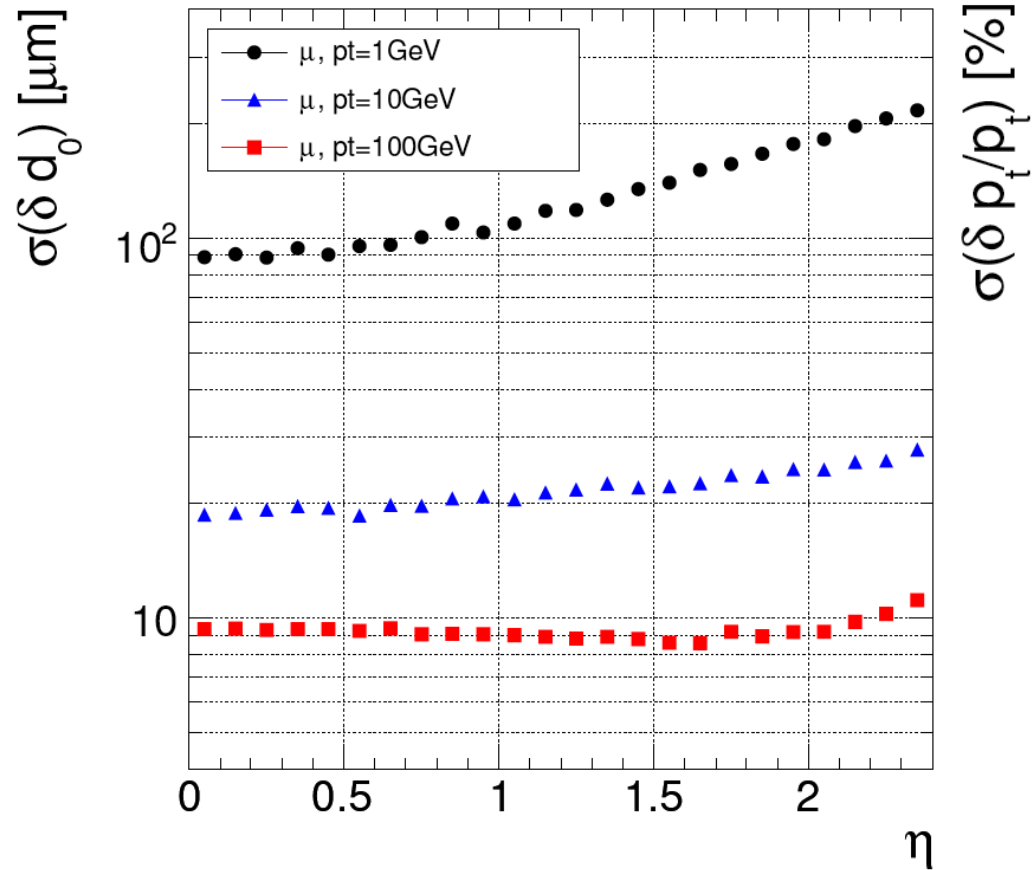
Note growth of σ with R



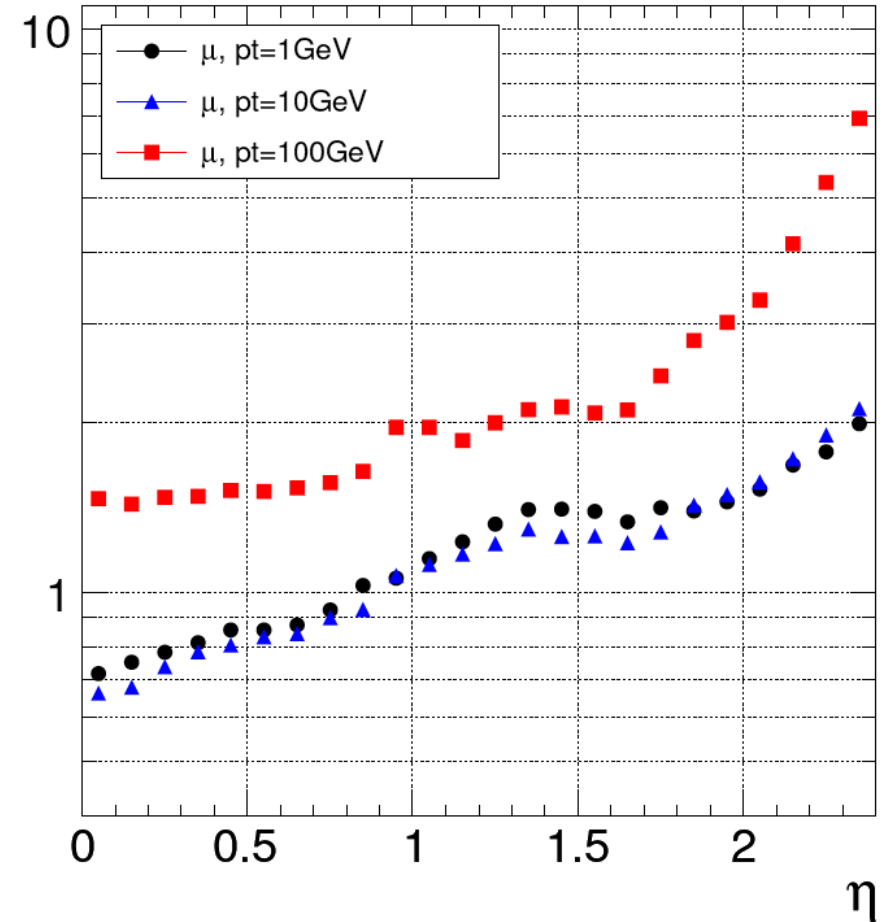
# Example results from **full** simulation

From CMS detector paper & Physics TDR

Transverse impact parameter

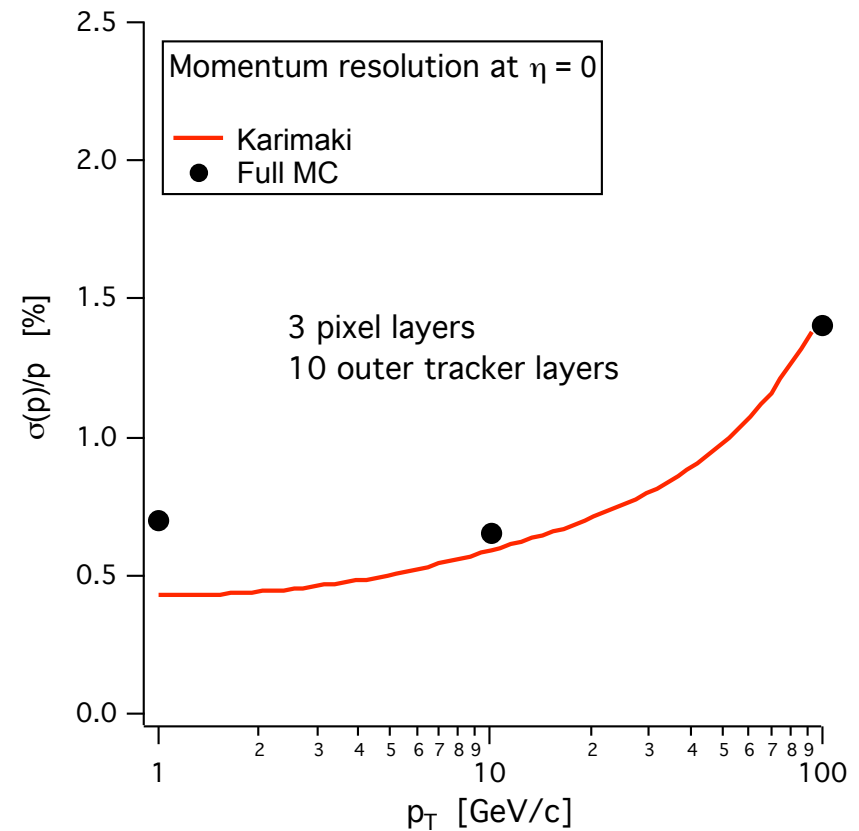
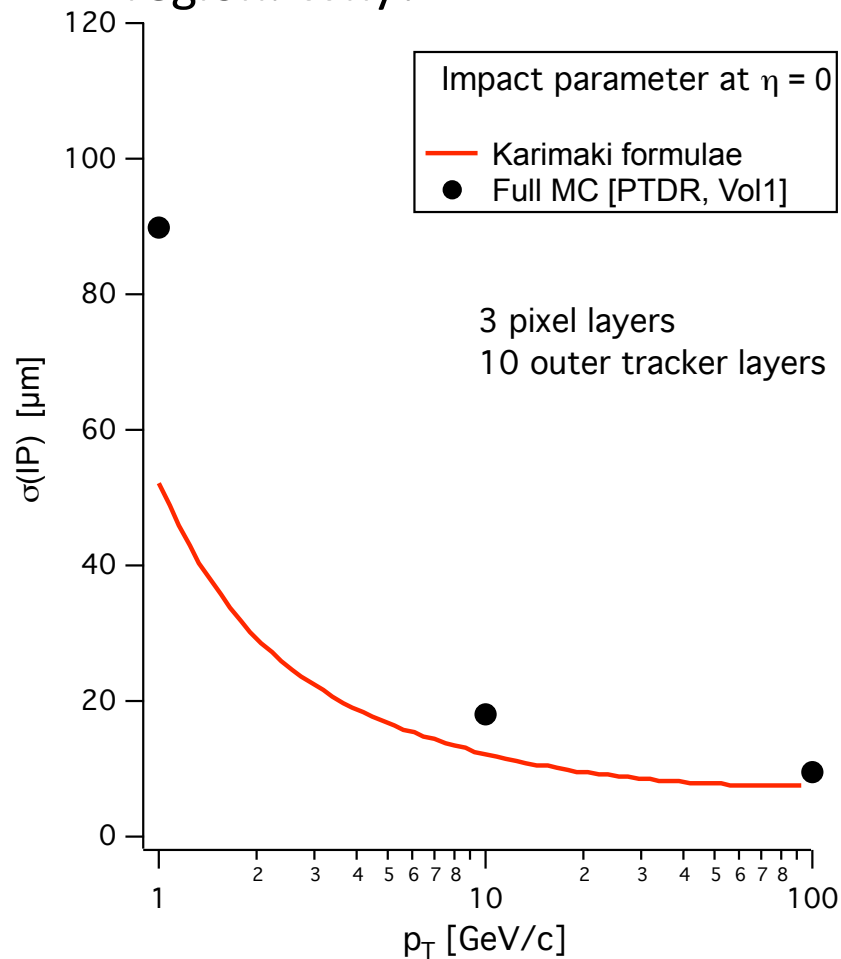


Momentum resolution

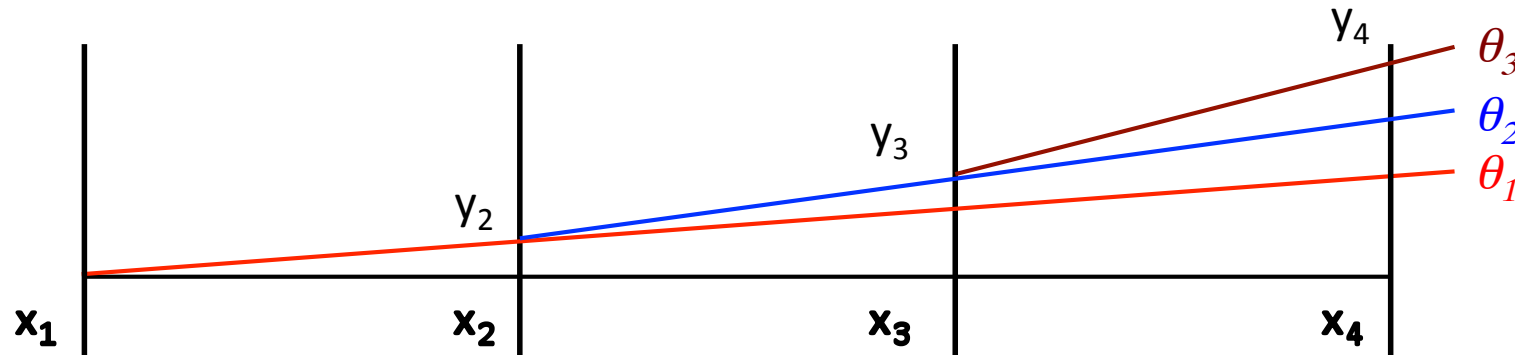


## Results at $\eta = 0$

Calculation using Karimäki formulae correctly reproduces results where measurement errors dominate, but not in multiple scattering region. Why?



# Correlations from multiple scattering



- $C_{11} = \langle y_1 y_1 \rangle = \sigma_1^2$        $\sigma_1 = \text{intrinsic measurement error}$
  - $C_{22} = \langle y_2 y_2 \rangle = \langle x_{21} \theta_1 x_{21} \theta_1 \rangle = x_{21}^2 \langle \theta_1^2 \rangle$     (+  $\sigma_2^2$  if not negligible, etc)
  - $C_{33} = \langle y_3 y_3 \rangle = \langle (x_{31} \theta_1 + x_{32} \theta_2)(x_{31} \theta_1 + x_{32} \theta_2) \rangle = x_{31}^2 \langle \theta_1^2 \rangle + x_{32}^2 \langle \theta_2^2 \rangle$
  - $C_{21} = \langle y_2 y_1 \rangle = 0$
  - $C_{23} = \langle y_2 y_3 \rangle = \langle x_{21} \theta_1 (x_{31} \theta_1 + x_{32} \theta_2) \rangle = x_{21} x_{31} \langle \theta_1^2 \rangle$
- etc
- Does inclusion of off-diagonal terms affect result?

## Simple example

- 3 equally spaced, identical planes,  $\Delta x = \delta$ , multiple scattering dominates
- Straight line case. Minimise  $\chi^2 = \sum_{i,j} \varepsilon_i C_{ij}^{-1} \varepsilon_j$   $x_1 = 0, x_2 = \delta, x_3 = 2\delta$

Covariance matrix  $C = \begin{bmatrix} \sigma_1^2 & C_{12} & C_{13} \\ C_{12} & \sigma_2^2 & C_{23} \\ C_{13} & C_{23} & \sigma_3^2 \end{bmatrix}$   $\sigma^2(\theta) = \sum_{i,j} \frac{\partial \theta}{\partial y_i} C_{ij}^{-1} \frac{\partial \theta}{\partial y_j} = \frac{1}{\sum x_i x_j C_{ij}^{-1}}$

- without correlations:  $C$  &  $C^{-1}$

$$\begin{bmatrix} \sigma_1^2 & 0 & 0 \\ 0 & \delta^2 \langle \theta^2 \rangle & 0 \\ 0 & 0 & 5\delta^2 \langle \theta^2 \rangle \end{bmatrix} \begin{bmatrix} \frac{1}{\sigma_1^2} & 0 & 0 \\ 0 & \frac{1}{\delta^2 \langle \theta^2 \rangle} & 0 \\ 0 & 0 & \frac{1}{5\delta^2 \langle \theta^2 \rangle} \end{bmatrix}$$

$$\sigma^2(\theta) = \frac{5}{9} \langle \theta^2 \rangle$$

- with correlations:  $C$  &  $C^{-1}$

$$\begin{bmatrix} \sigma_1^2 & 0 & 0 \\ 0 & \delta^2 \langle \theta^2 \rangle & 2\delta^2 \langle \theta^2 \rangle \\ 0 & 2\delta^2 \langle \theta^2 \rangle & 5\delta^2 \langle \theta^2 \rangle \end{bmatrix} \begin{bmatrix} \frac{1}{\sigma_1^2} & 0 & 0 \\ 0 & \frac{5}{\delta^2 \langle \theta^2 \rangle} & \frac{-2}{\delta^2 \langle \theta^2 \rangle} \\ 0 & \frac{-2}{\delta^2 \langle \theta^2 \rangle} & \frac{1}{\delta^2 \langle \theta^2 \rangle} \end{bmatrix}$$

$$\sigma^2(\theta) = \langle \theta^2 \rangle$$

at least proves that correlations can't be ignored

## Errors with correlation terms

- To calculate covariance matrix  $W$  and inverse in full, replace

$$W_{kl} = \sum_i w_i \frac{\partial \varepsilon_i}{\partial \alpha_k} \frac{\partial \varepsilon_i}{\partial \alpha_l} \quad \text{with} \quad W_{kl} = \sum_{i,j} \frac{\partial \varepsilon_i}{\partial \alpha_k} C_{ij}^{-1} \frac{\partial \varepsilon_j}{\partial \alpha_l}$$

Terms needed already provided by Karimäki:

$$\frac{\partial \varepsilon_i}{\partial \rho} = \frac{1}{2} r_i^2 \quad \frac{\partial \varepsilon_i}{\partial \phi} = -x_i \quad \frac{\partial \varepsilon_i}{\partial d} = 1 + \rho y_i$$

- The solutions are the diagonal terms of  $W^{-1}$

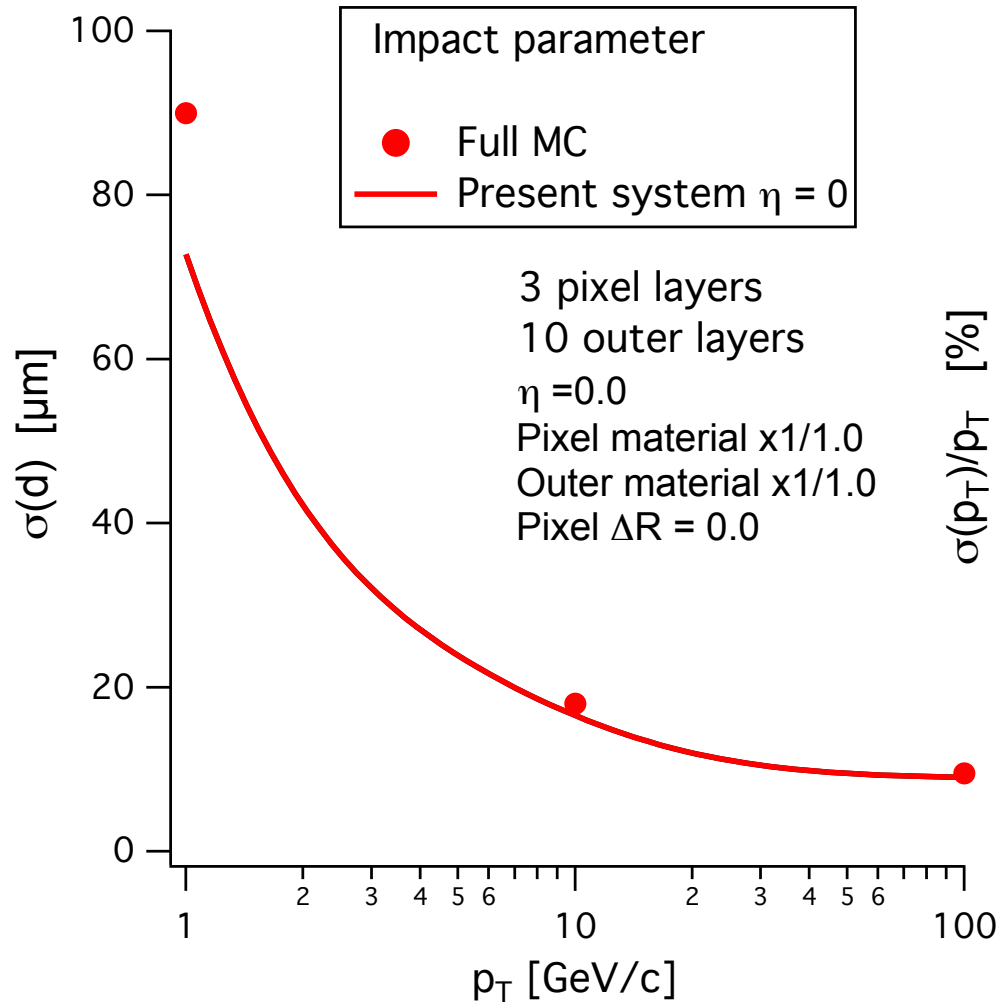
$$\sigma^2(\rho) = W_{11}^{-1} \quad \sigma^2(\phi) = W_{22}^{-1} \quad \sigma^2(d) = W_{33}^{-1}$$

- with the origin chosen to be on the beam line
  - The beam pipe is a dummy measurement plane to correctly include its off-diagonal contributions
  - This changed some of the results I have shown previously

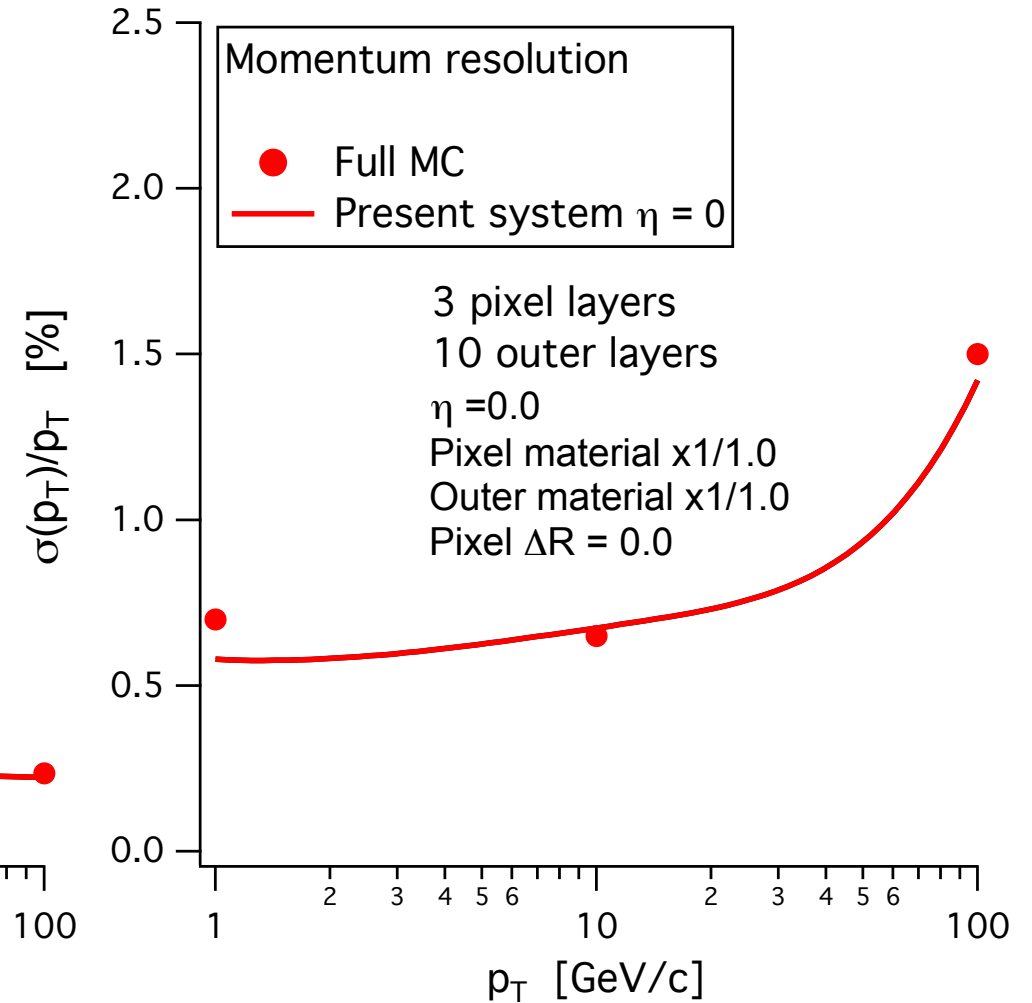
# Results from calculation

$\eta = 0$

## Transverse impact parameter

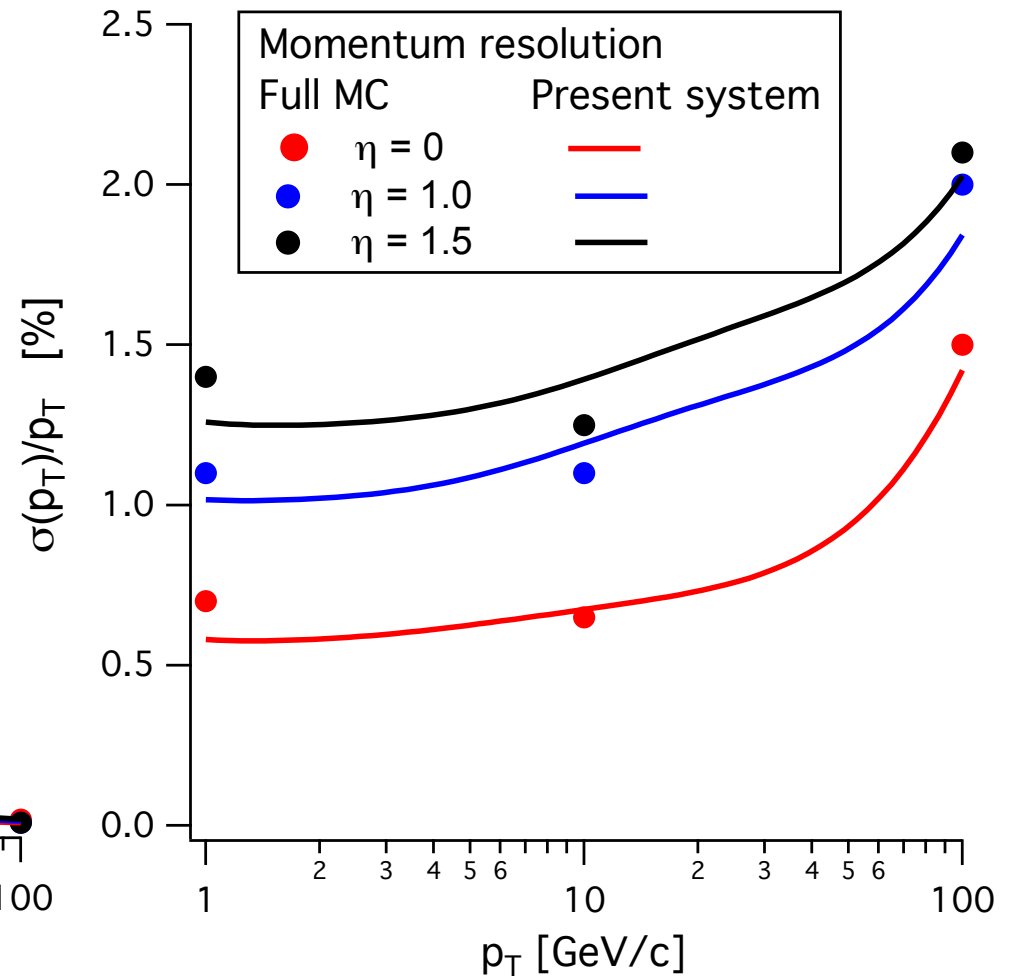
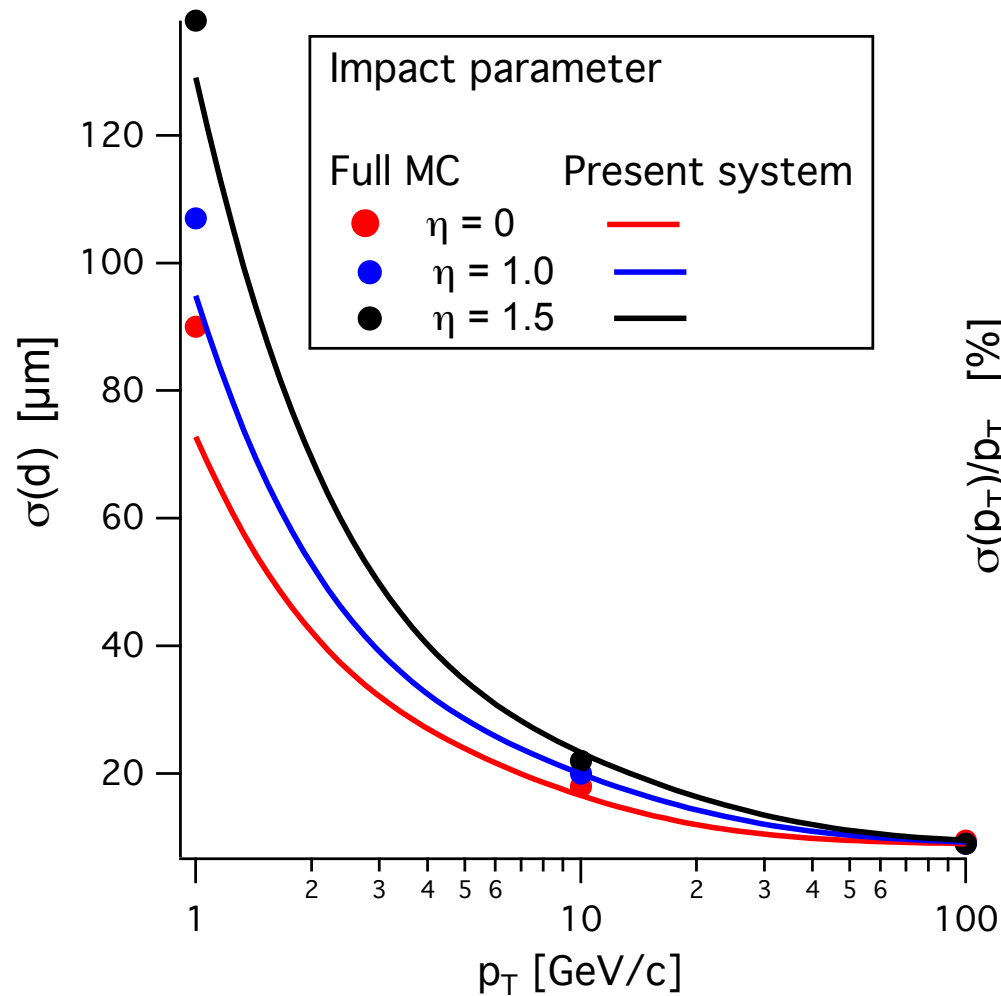


## Momentum resolution



## Results from calculation (ii)

Added numerical interpolation of material for  $\eta > 0$

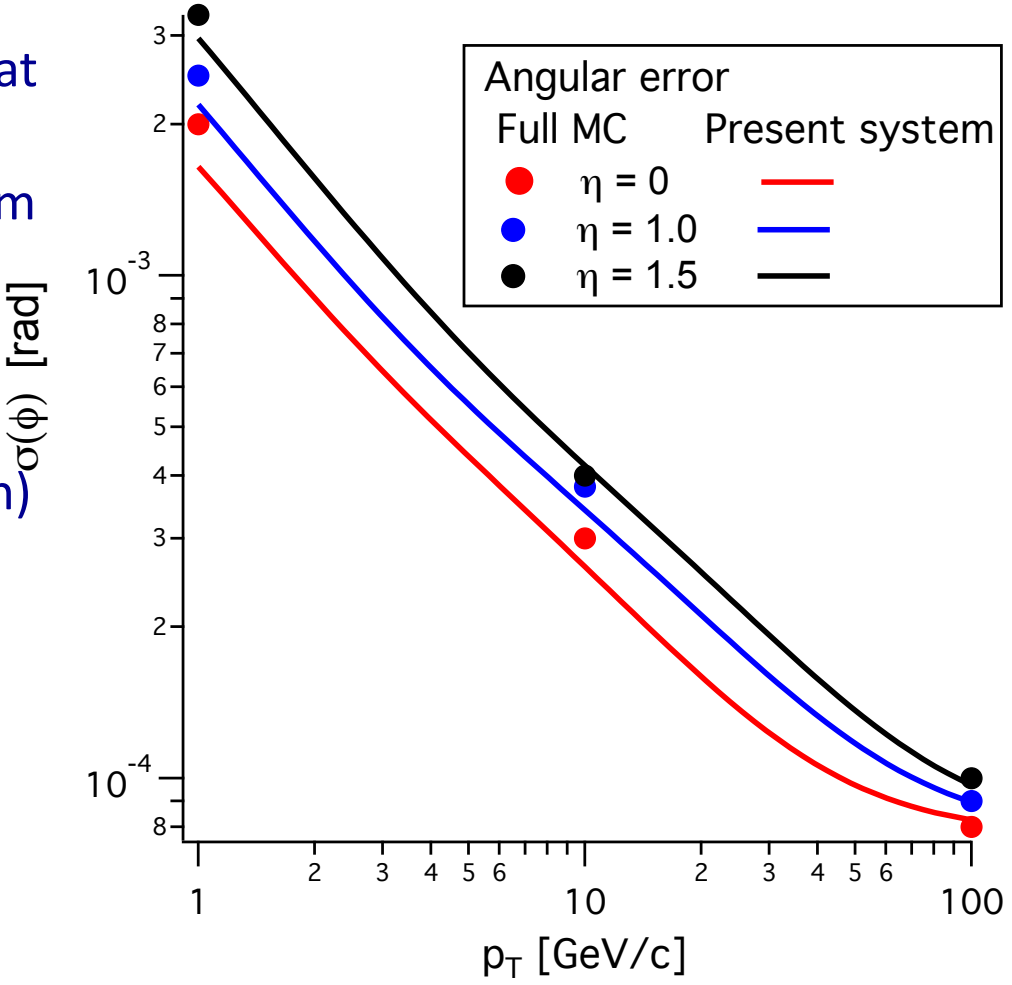


# Results from calculation (iii)

Angular resolution also calculated

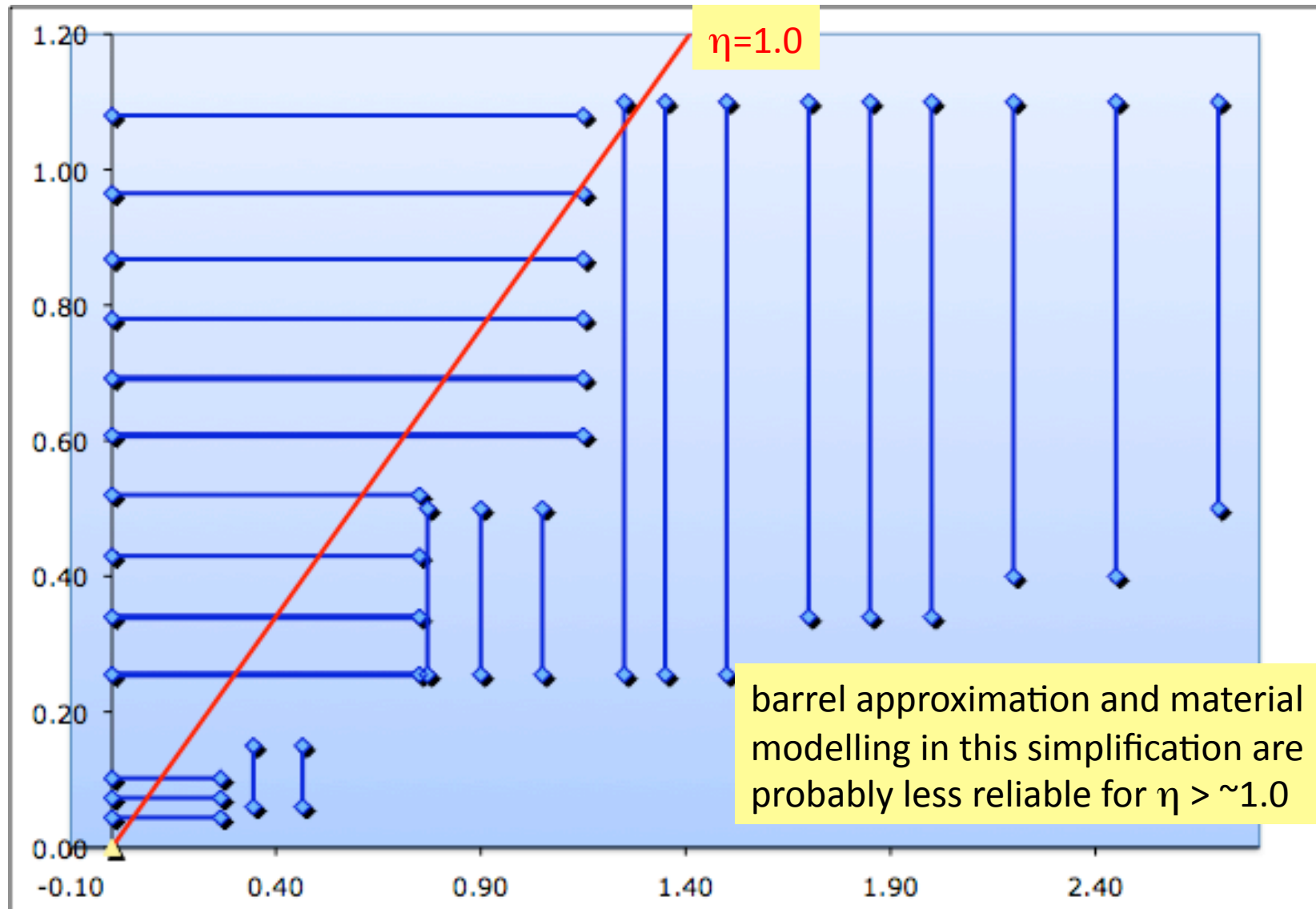
NB small but noticeable sensitivity at low p to changes in pixel point resolution in layer 1, eg 10- $\rightarrow$ 15 $\mu$ m

However, this is at the limit of the achievable precision in the modelling (even in full simulation)





# Scale view of Tracker



# Impact error from pixels alone

Physics TDR Vol 1

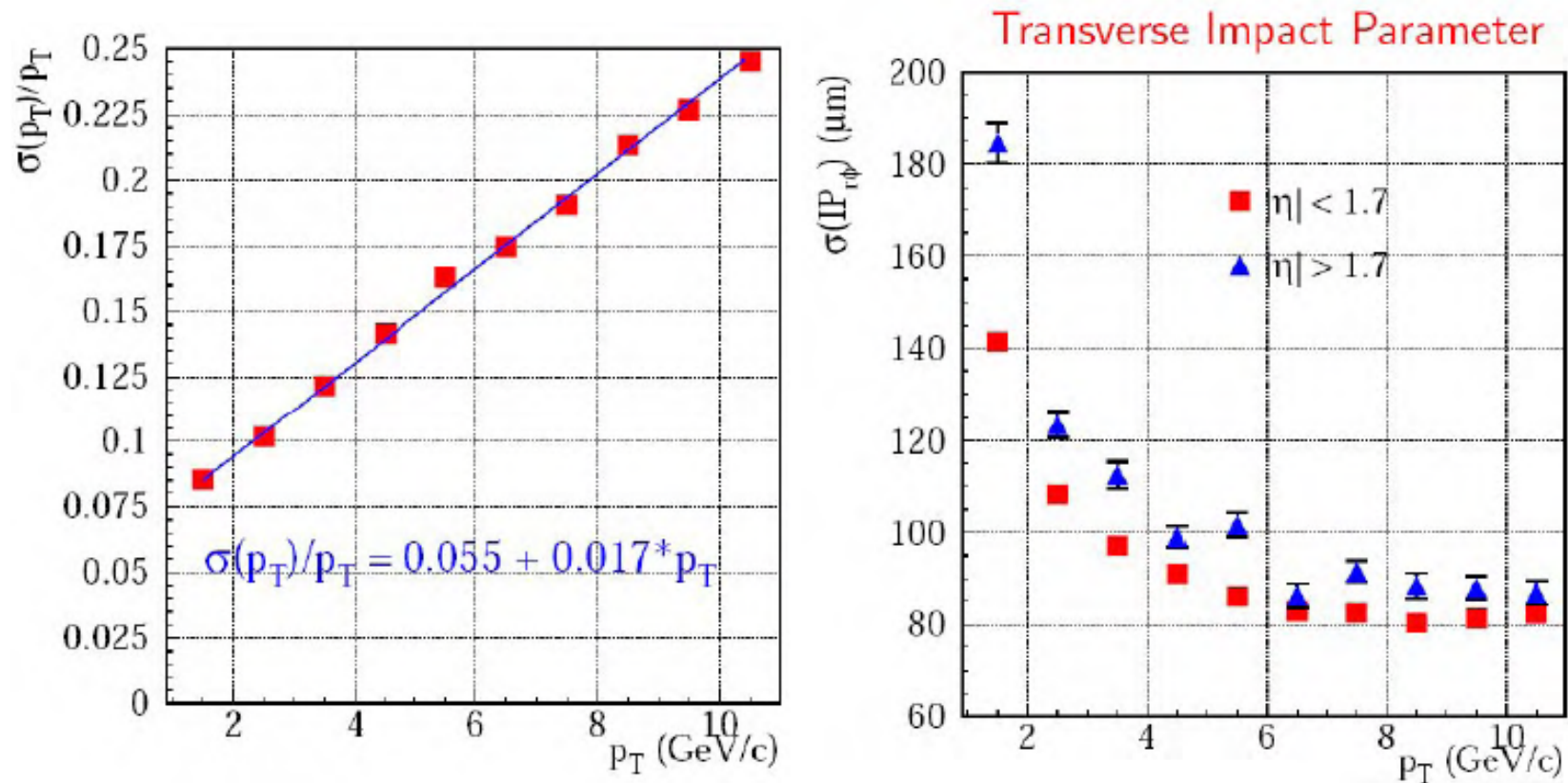
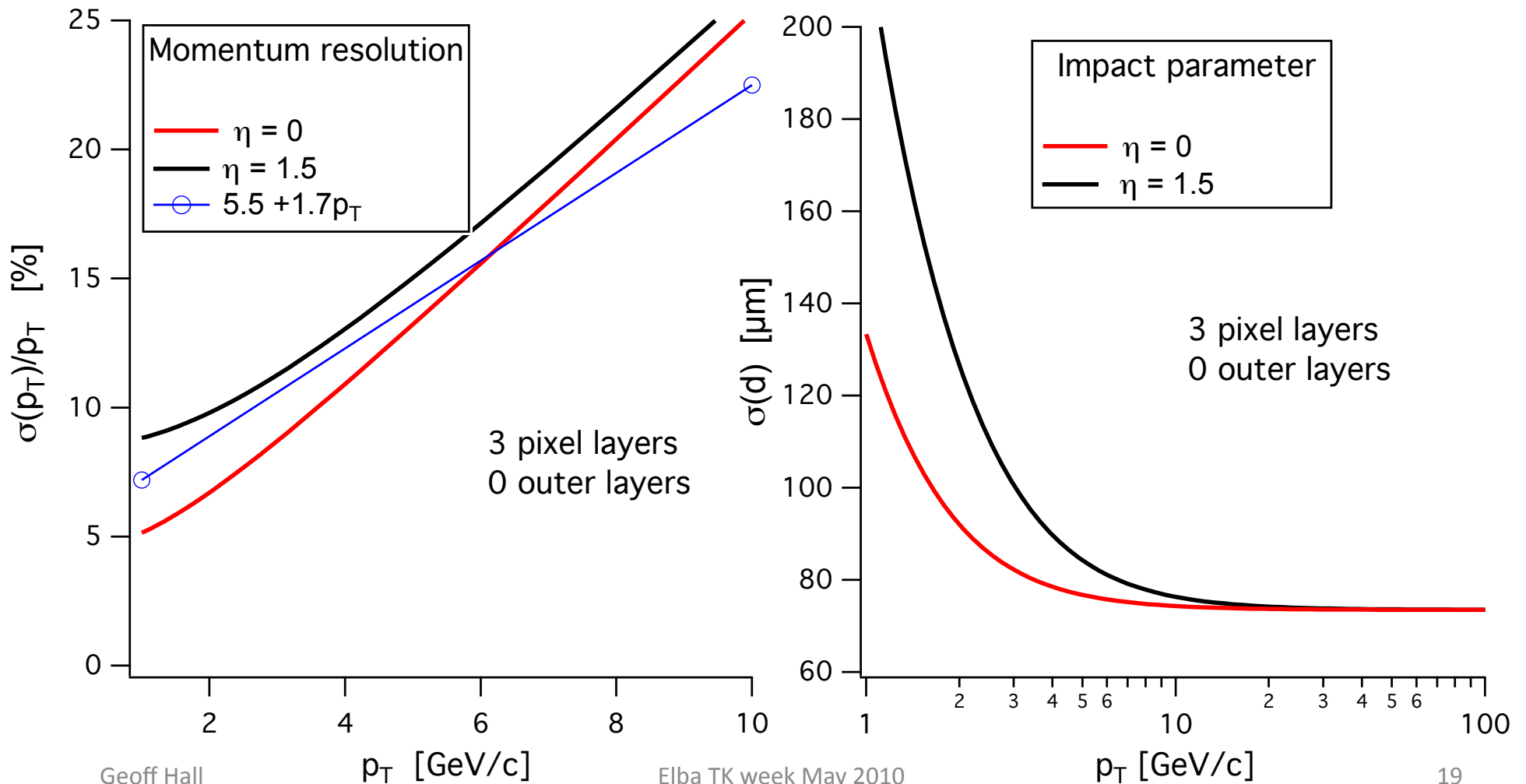


Figure 6.17: Transverse momentum (left) and transverse impact parameter (right) resolution for single muon tracks, created directly from hit triplets.

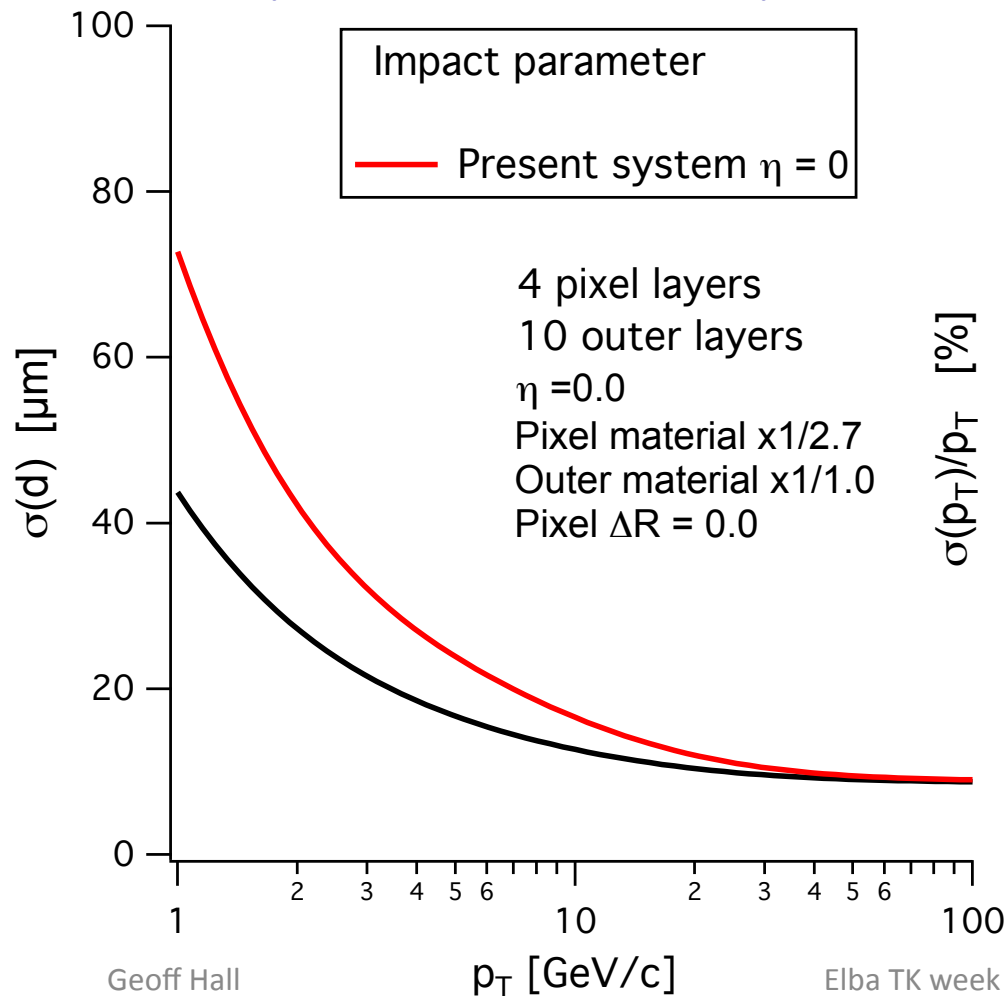
# Present pixel stand alone

- Quite good agreement in both IP and momentum resolution
  - Proper matrix treatment removes discrepancy I thought due to hit merging

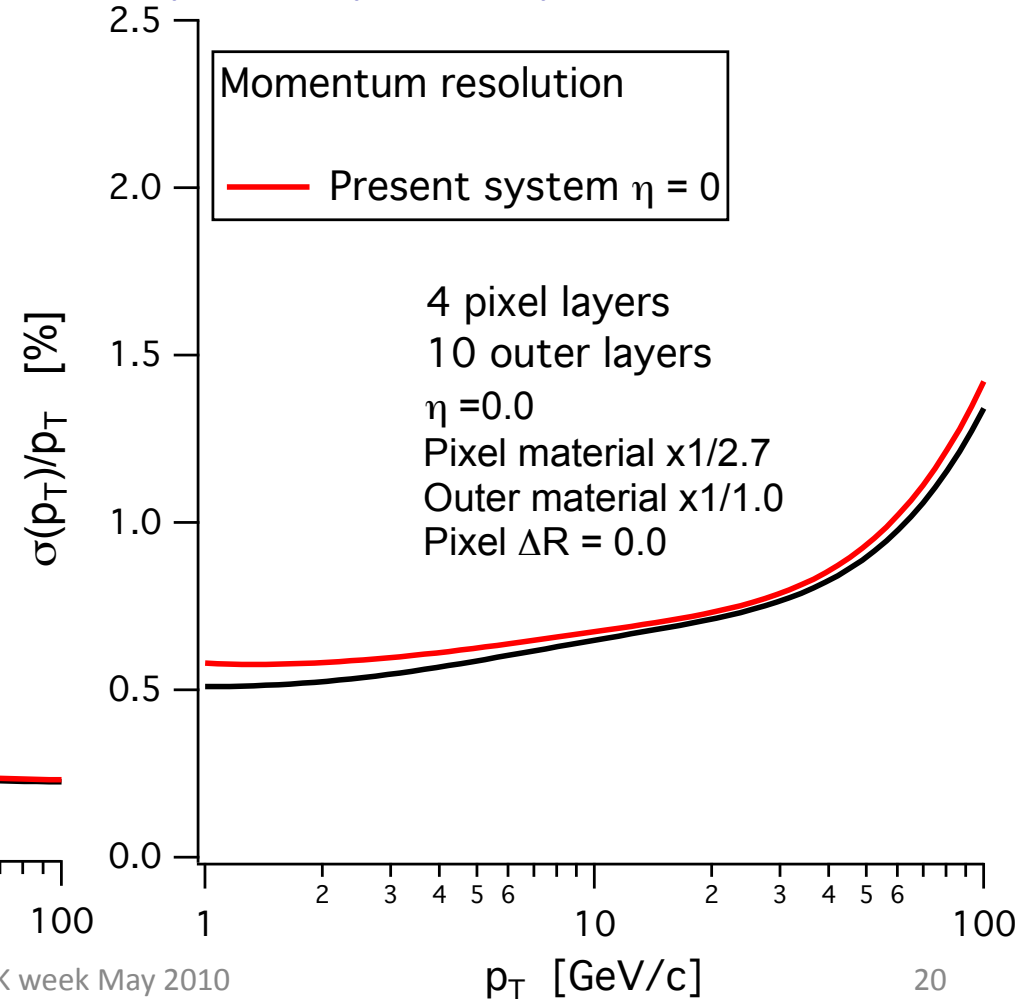


# Preview of future

- Some indication of benefits of 4 layer system
  - reduced radii: 2.5 cm beam pipe, pixels: 3.9, 6.8, 10.9, 16.0 cm
  - pixel material reduced by factor 2.7 compared to present system



Elba TK week May 2010

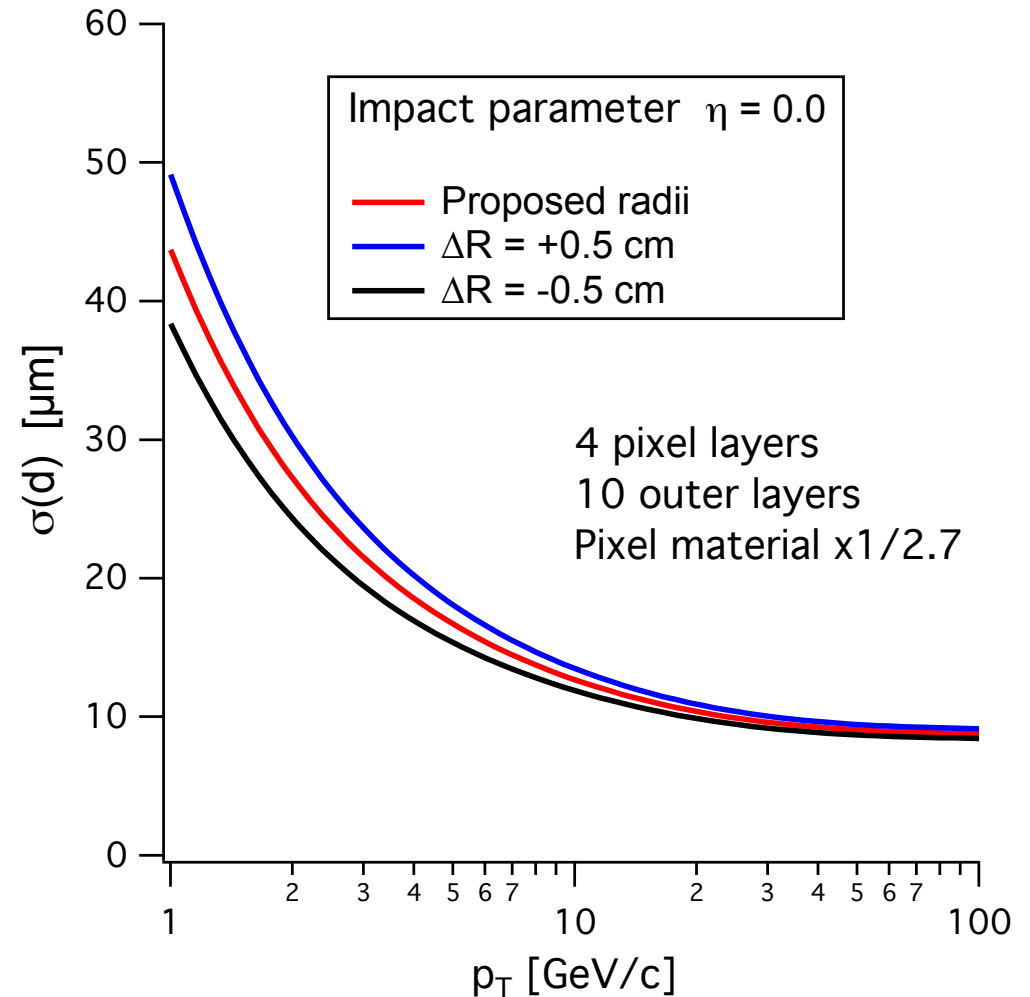


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Geoff Hall

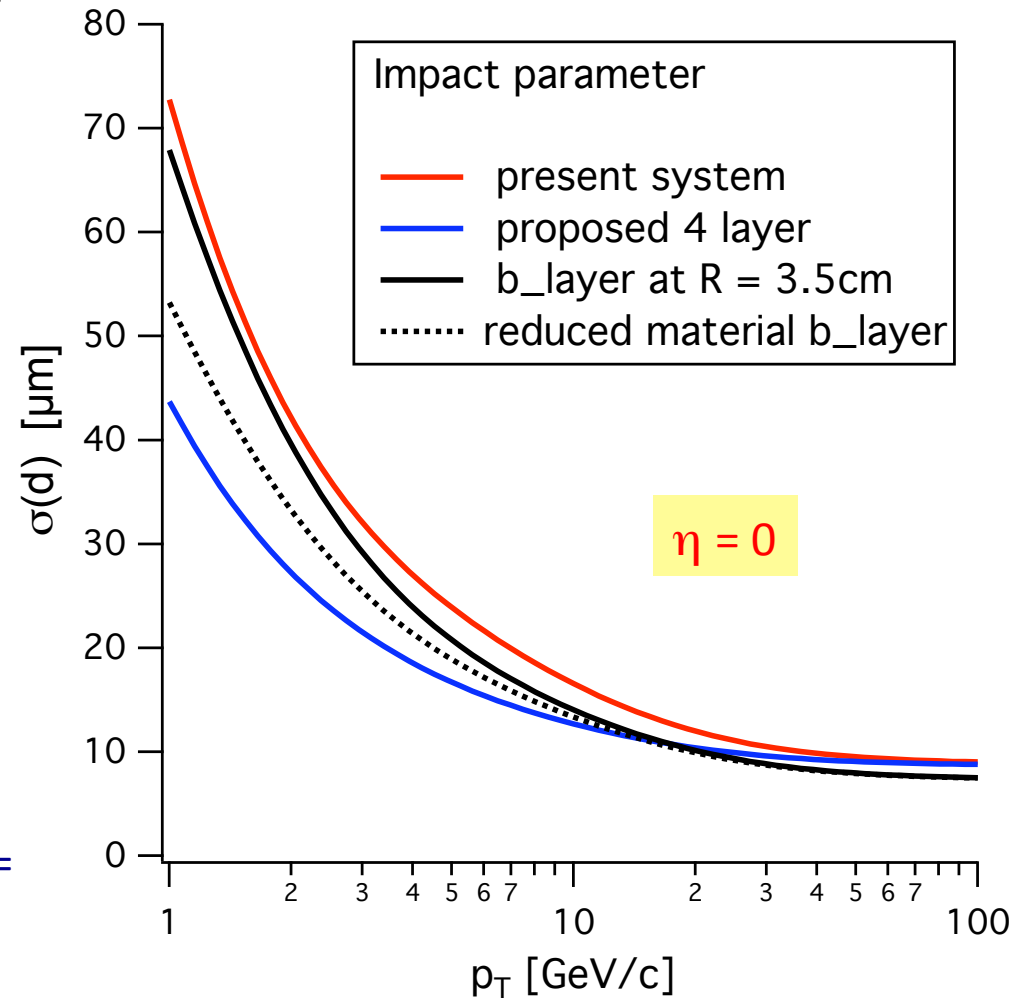
# Effect of shrinking radially?

- All layers move in or out by fixed amount
- If material reduction is as expected, then further benefits from reducing radial dimensions appear to be limited



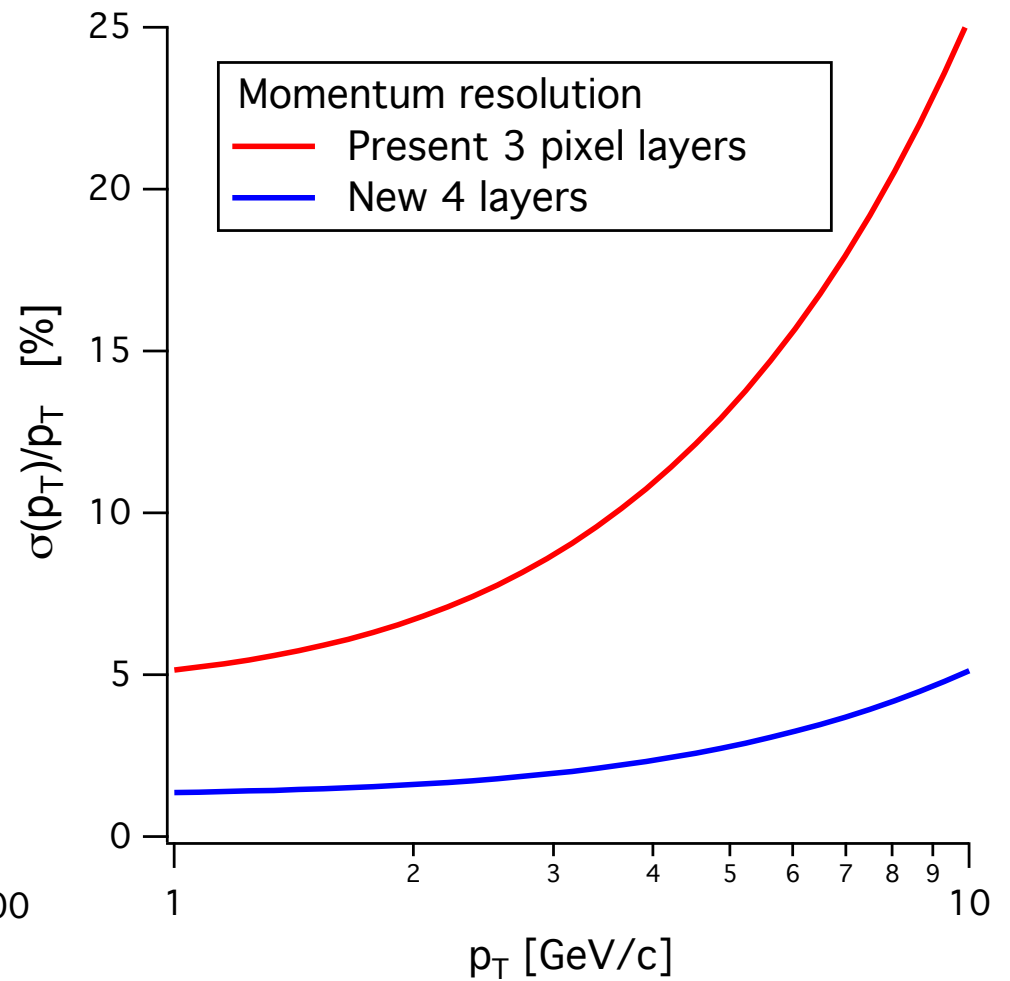
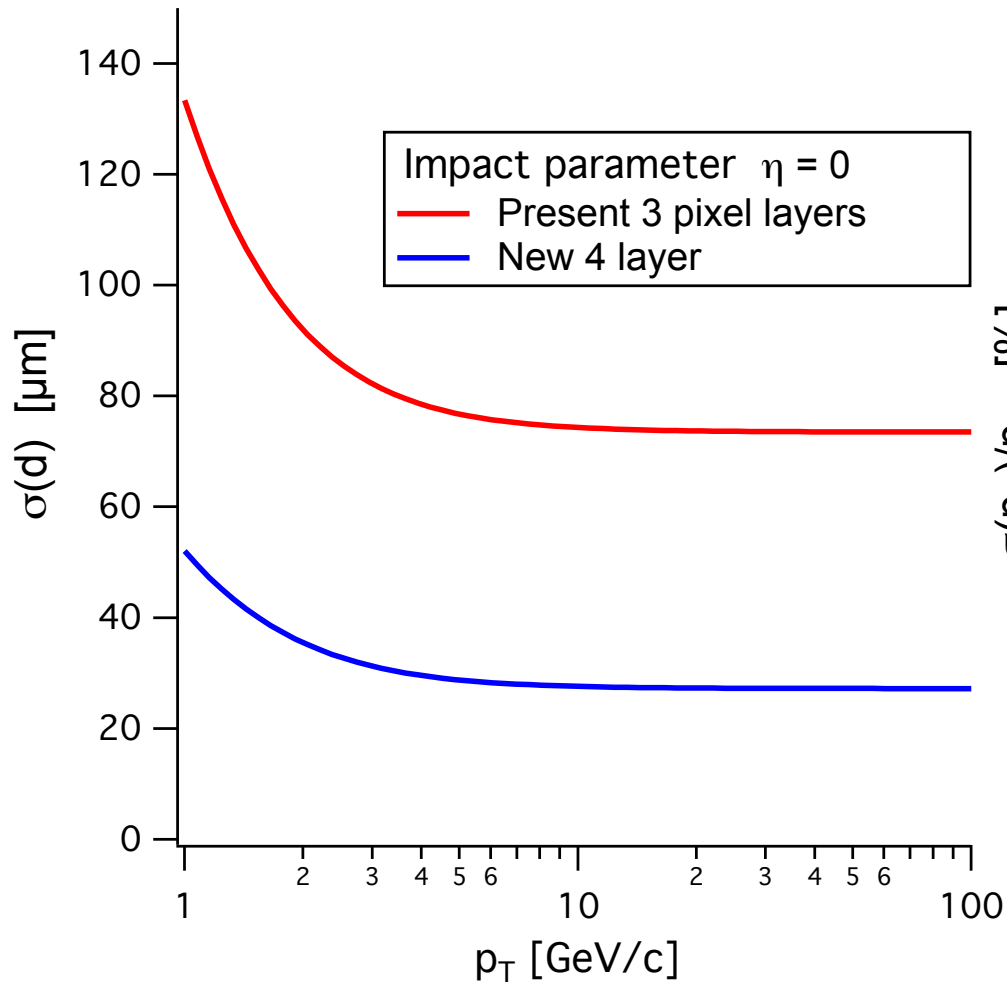
# Use of b-layer

- Suppose we tried ATLAS approach?
- Assume b-layer could be inserted at  $R = 3.5\text{cm}$ 
  - and other layers remain at:
    - $R = 4.4, 7.3, 10.0$
- Two variants of b-layer
  - with present material
  - material reduced by factor 2.7
  - very small improvement for higher  $p_T$  is because of 2 inner points at  $R = 3.5$  &  $4.4$
  - disappears if pixel layer at  $4.4$  dies



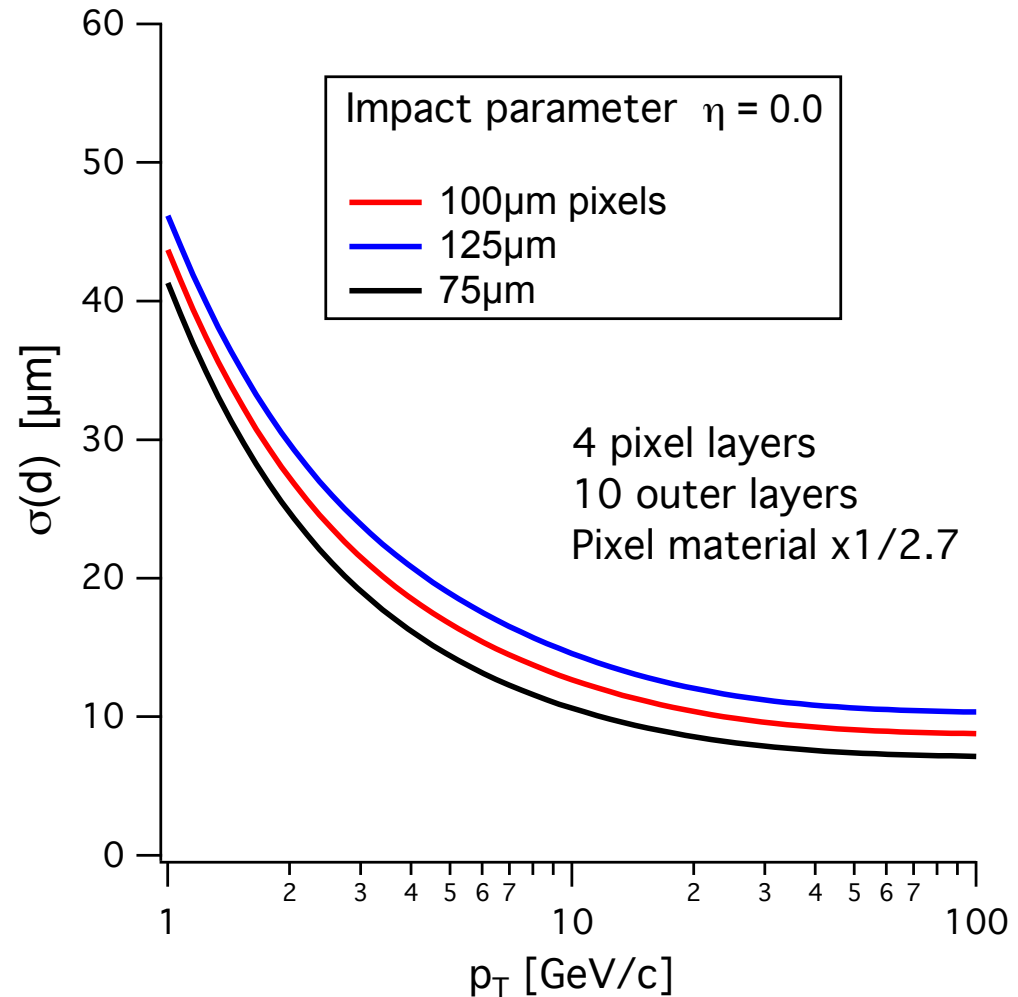
# Stand alone pixels

- Also benefit, if useful...



## Smaller pixels?

- Assume  $r$ - $\phi$  resolution scales with pixel size
  - also indicates effect of degradation due to radiation damage
  - scope for further detailed evaluation if useful





# Conclusions

- Full covariance matrix calculation of errors gives good insight into possible layout variations
  - basically, emulates real life or full Monte Carlo
  - essential where multiple scattering errors are important
  - allows very fast comparison between different options, including adding/removing layers, changing material, etc
  - calculations can play a role in optimising and exploring tracker designs
  - can be added to Layout Tool for many more details to be evaluated
- Material degrades performance (you will be surprised to learn!)
  - in pixels degrades mainly impact parameter
  - in outer tracker affects mainly momentum resolution
  - innermost radial point is most important
- Many more interesting cases can be studied
  - and complements full simulations (of fewer options)

## For reference: Covariance matrix W

$$W_{kl} = \sum_{i,j} \frac{\partial \varepsilon_i}{\partial \alpha_k} C_{ij}^{-1} \frac{\partial \varepsilon_j}{\partial \alpha_l}$$

$$\frac{\partial \varepsilon_i}{\partial \rho} = \frac{1}{2} r_i^2$$

$$\frac{\partial \varepsilon_i}{\partial \phi} = -x_i$$

$$\frac{\partial \varepsilon_i}{\partial d} = 1 + \rho y_i$$

$$W_{11} = \sum_{i,j} \frac{1}{4} r_i^2 r_j^2 C_{ij}^{-1}$$

$$W_{22} = \sum_{i,j} x_i x_j C_{ij}^{-1}$$

$$W_{33} = \sum_{i,j} (1 + \rho y_i)(1 + \rho y_j) C_{ij}^{-1}$$

$$W_{12} = \sum_{i,j} -\frac{1}{2} r_i^2 x_j C_{ij}^{-1}$$

$$W_{13} = \sum_{i,j} \frac{1}{2} r_i^2 (1 + \rho y_j) C_{ij}^{-1}$$

$$W_{23} = \sum_{i,j} -x_i (1 + \rho y_j) C_{ij}^{-1}$$

$$\sigma^2(\rho) = W_{11}^{-1}$$

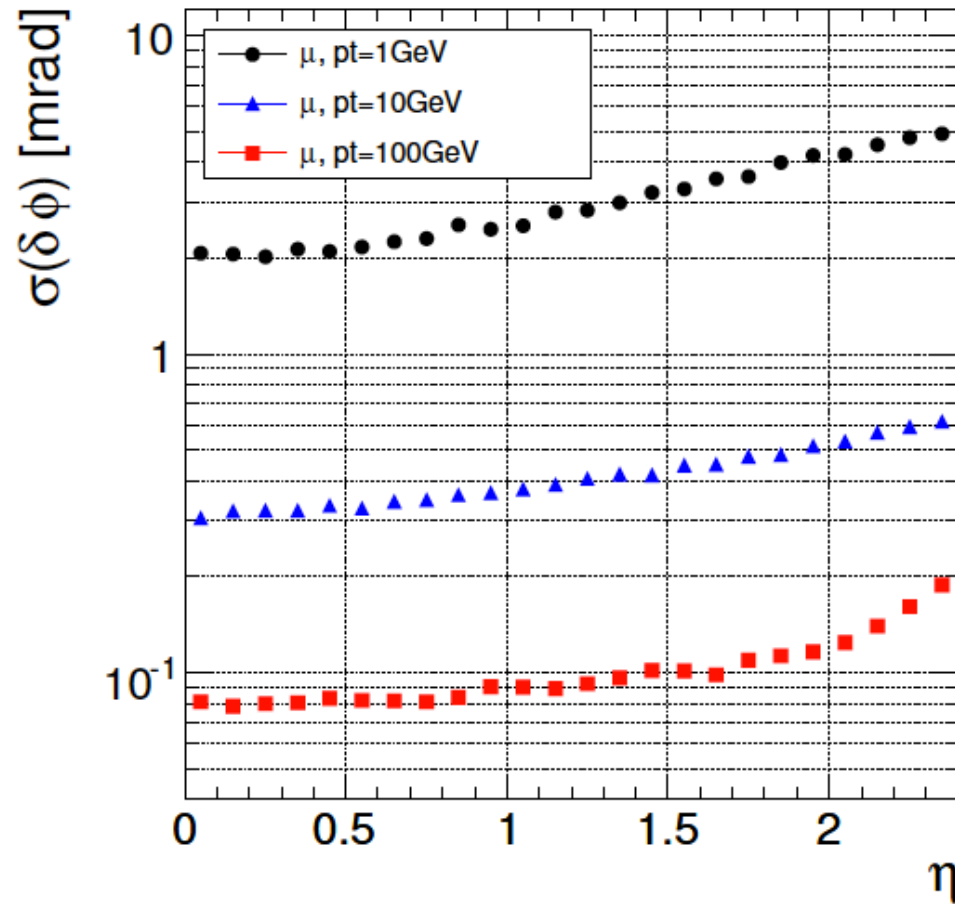
$$\sigma^2(\phi) = W_{22}^{-1}$$

$$\sigma^2(d) = W_{33}^{-1}$$

# Impact error from full simulation

From CMS detector paper & Physics TDR v1

Angular resolution



Longitudinal impact error

